



Inferred Measurements of the Zodiacal Light Absolute Intensity through Fraunhofer Absorption Line Spectroscopy with CIBER

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Abstract

Scattered sunlight from the interplanetary dust (IPD) cloud in our solar system presents a serious foreground challenge for spectrophotometric measurements of the extragalactic background light (EBL). In this work, we report on inferred measurements of the absolute intensity of the zodiacal light (ZL) using the novel technique of Fraunhofer line spectroscopy on the deepest 8542 Å line of the near-infrared Ca II absorption triplet. The measurements are performed with the narrow band spectrometer (NBS) on board the Cosmic Infrared Background Experiment sounding rocket instrument. We use the NBS data to test the accuracy of two ZL models widely cited in the literature, the Kelsall and Wright models, which have been used in foreground removal analyses that produce high and low EBL results respectively. We find a mean reduced $\chi^2 = 3.5$ for the Kelsall model and $\chi^2 = 2.0$ for the Wright model. The best description of our data is provided by a simple modification to the Kelsall model, which includes a free ZL offset parameter. This adjusted model describes the data with a reduced $\chi^2 = 1.5$ and yields an inferred offset amplitude of $46 \pm 19 \text{ nW m}^{-2} \text{ sr}^{-1}$ extrapolated to 12500 Å. These measurements elude to the potential existence of a dust cloud component in the inner solar system whose intensity does not strongly modulate with the Earth's motion around the Sun.

Unified Astronomy Thesaurus concepts: [Cosmology \(343\)](#)

1. Introduction

Measurements of the absolute intensity and spectrum of the extragalactic background light (EBL) at optical and near-infrared (NIR) wavelengths capture the redshifted energy released from all nucleosynthesis and gravitational accretion processes throughout cosmic history (Hauser & Dwek 2001). In addition to known galaxy populations, emission sources that contribute to the EBL include the first stellar objects and primordial black holes. If measured with sufficient precision, the EBL spectrum can be used to constrain models of galaxy formation and evolution, connecting energy density to star formation, metal production, and gas consumption as reviewed in Cooray (2016). The EBL also provides an important cosmic consistency test. It allows for a direct comparison of the measured amplitude in the total aggregate signal and the integrated light from all galaxies (IGL) that can be measured directly from deep photometric surveys of individually detected sources. Any discrepancy implies the presence of additional emission from unaccounted components. Diffuse sources could arise during reionization due to recombination radiation, such

as a Ly α background, as well as more exotic sources such as dark matter particle decays and annihilation.

Precise absolute spectrophotometry of the NIR EBL has proven elusive, predominantly due to the bright foreground from sunlight scattered off interplanetary dust (IPD) in our own solar system, commonly referred to as the zodiacal light (ZL). Apart from making photometry measurements out of the ecliptic plane or past the orbit of Jupiter (Matsuoka et al. 2011; Zemcov et al. 2017; Lauer et al. 2021), absolute measurements require the accurate subtraction of the ZL foreground. Recent analyses of New Horizons data taken beyond 42 au from the Sun have reported a potential detection of an excess over the IGL in the optical (Lauer et al. 2021).

Other groups have sought to quantify the absolute level of the EBL by concentrating on indirect measurements such as searching for the imprint left by the EBL on the spectra of bright gamma-ray sources (Desai et al. 2019). Indirect high-energy measurements suffer from their own independent set of systematic errors and are therefore very useful as a consistency check.

Data from the NIR photometer on board NASA's Diffuse InfraRed Background Explorer (DIRBE) in the early 1990s were used to generate a geometrical model of the IPD. The Kelsall et al. (1998) model was generated by characterizing the annual modulation of the ZL signal, arising from variations in the integrated dust column density toward a given background



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field due to the inclination of the dust cloud with respect to the Earth’s orbit. Space-based absolute photometry measurements which rely on this model have yielded EBL estimates of $\sim 60 \text{ nW m}^{-2} \text{ sr}^{-1}$ at $1.25 \mu\text{m}$ (Cambr esy et al. 2001; Matsumoto et al. 2015), although Matsumoto et al. (2015) allow for a relative calibration difference. A background of this magnitude is difficult to reconcile with the X-ray background and the present-day abundance of metals (Madau & Silk 2005).

Wright (2001) produced a ZL model based on DIRBE data under the assumption that the ZL accounts for the entire sky brightness at $25 \mu\text{m}$. This model, intended to provide a lower limit on the EBL, produced estimates marginally consistent with the IGL (Levenson et al. 2007). Recent work from the low resolution spectrometer (LRS) on board the Cosmic Infrared Background Experiment (CIBER) examined the behavior of the EBL from NIR toward the optical under a variety of foreground assumptions (Matsuura et al. 2017). These results suggested a lower limit EBL that was slightly brighter than the IGL with a spectrum markedly redder than the ZL.

In this paper, we employ a Fraunhofer line technique to assess the absolute intensity of the ZL foreground. As the ZL is composed solely of scattered solar emission shortward of $\sim 3 \mu\text{m}$, Fraunhofer absorption lines with well understood and stable equivalent widths can be used to trace the brightness, based on the solar spectrum. By accurately measuring the line depth, one can infer the continuum amplitude of the ZL signal alone, independent of a spectrally flat offset.

The Fraunhofer technique was pioneered by Dube et al. (1977) to determine the EBL at optical wavelengths. More recently, Bernstein et al. (2002a, 2002b, 2002c), used this technique by combining space-based photometry from the Hubble Space Telescope with estimates of the ZL intensity from Fraunhofer line measurements made from the ground. Initial reports of a significant bright EBL detection were later softened as the result of increased scrutiny on systematics resulting from atmospheric and ground reflectance effects (Mattila 2003; Bernstein 2007). This highlights the importance of making absolute photometry measurements from space. Other recent work has applied Fraunhofer spectroscopy to constrain the dynamics in the IPD (Ipatov et al. 2008).

In this paper, we report a ZL absolute intensity measurement from the custom designed Narrow Band Spectrometer (NBS) with a band targeting the 8542 \AA Ca II Fraunhofer line. The instrument is one of four on board the CIBER sounding rocket payload (Zemcov et al. 2013), which has been flown successfully four times. The detailed design and sensitivity of the NBS is given in Korngut et al. (2013). This paper reports the detailed analysis of the CIBER NBS science data and the implications for the intensity of the ZL foreground in the NIR.

2. NBS

The CIBER NBS telescope is a refractive wide field camera with a 75 mm primary aperture. In order to obtain the necessary signal-to-noise on the ZL in a short sounding rocket flight, a large etendue was required, yielding an instantaneous field of view (FOV) of 8.5×8.5 sampled by a 256×256 pixel HgCdTe array.¹¹ A tipped interference filter in front of the camera generates a narrow bandpass whose central wavelength varies as a function of angle of incidence across the field of

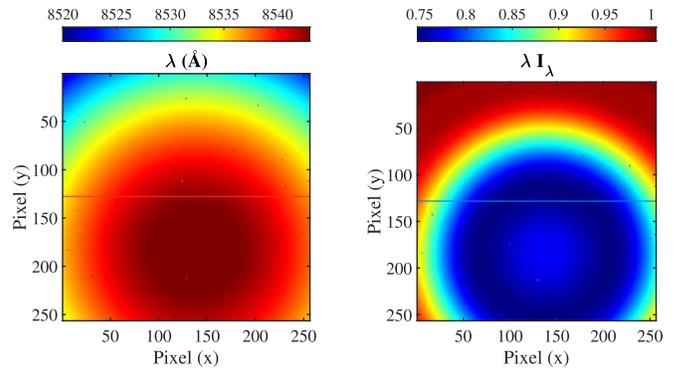


Figure 1. Left: the tipped interference filter creates a radially varying central wavelength response across the detector. Right: the continuum normalized solar absorption spectrum as measured at the focal plane of the NBS.

view. In this measurement scheme, the spectrum of a uniformly illuminating source such as the ZL can be obtained by extracting the photocurrent level as a function of the radial distance from the boresight, including a shift in angle equivalent to the amplitude of the filter’s tip.

The narrow bandpass was optimized specifically to measure spectral regions both on and off the Ca II absorption line without sacrificing sensitivity by extending the spectral range beyond what is necessary to accurately probe the line depth. The chosen range spans $8520 \text{ \AA} < \lambda < 8545 \text{ \AA}$ with a resolving power $R = \frac{\lambda}{\Delta\lambda} = 1120$. In this scheme, an absorption feature in a uniformly illuminating ZL appears as an annular dip. An illustration of the basic measurement at the NBS focal plane is given in Figure 1. For a detailed discussion of the instrument design, see Korngut et al. (2013).

3. Rocket Flights

The data presented here were acquired over three suborbital rocket flights. The first two were on board NASA’s Black Brant IX two-stage vehicles launched from White Sands Missile Range in New Mexico. These flights achieved apogees of $\sim 330 \text{ km}$, the first in 2010 July and the second flown in 2012 March. Both flights displayed nominal performance and the instrument was recovered with no damage. For CIBER’s final flight, the payload was flown on a Black Brant XII four stage vehicle, from NASA’s Wallops Flight Facility off the coast of Virginia in 2013 June. The Black Brant XII provided a much higher apogee of $\sim 600 \text{ km}$ and nearly double the time available for science data acquisition above 250 km , though the payload was intentionally not recovered.

4. Field Selection

We selected fields to optimize a range of criteria, in conjunction with the goals of the other instruments on board CIBER. They are located at a range of Galactic and ecliptic latitudes, modulating the relative contributions of the ZL and other sources of Ca II absorption from the integrated stellar light (ISL) and diffuse Galactic light (DGL), which are discussed in detail in Sections 6.2, 6.1.1, and 6.1.2. The three suborbital rocket flights took place during different phases of the Earth’s orbit around the Sun. Due to the inclination of the IPD cloud in the ecliptic plane, fields that have identical extrasolar backgrounds will have different ZL intensities, as the column density we look through varies. The fields are listed in

¹¹ PICNIC detectors manufactured by Teledyne Technologies (<http://www.teledyne.com/>).

Table 1
Selected Target Fields

Field	α (hr)	δ (deg)	Flight	Exposure (s)
NEP	18.06	66.10	2010 Jul	63
Bootes A	14.55	34.58	2010 Jul	59
Bootes B	14.46	33.08	2010 Jul	32
Elat 30A	15.77	09.29	2012 Mar	24
Bootes B	14.45	33.02	2012 Mar	47
Elat 10	12.69	08.32	2013 Jun	46
Elat 30B	12.87	28.29	2013 Jun	47
Bootes B	14.48	33.50	2013 Jun	52
Elais-N1	16.19	54.34	2013 Jun	47

Note. Data were collected across three sounding rocket flights. The fields were selected to span a range of both ecliptic and Galactic latitudes to modulate the relative contributions of ZL, ISL, and DGL.

Table 1, along with the predicted $1.25 \mu\text{m}$ intensities from the Kelsall and Wright models.

5. Data Reduction

The raw data arriving via radio frequency telemetry consist of a series of timestamped PICNIC detector frames sampled at 4 Hz. These frames are synchronized with housekeeping and event flags such as cold shutter status, coarse and fine target acquisition indicators, and a rocket door status. Photocurrent images of each field are generated using the sample-up-the-ramp method, or fitting a linear slope to the integrated charge for each pixel as a function of time. The first 10 frames after a reset are discarded from analysis to avoid transient response from charge injection. Before spectral extraction, the data are subject to a suite of processing steps, described in this section. Detailed information on the ancillary laboratory measurements used to generate various instrument data products can be found in Korngut et al. (2013).

5.1. Dark Current

The NBS is equipped with an optical shutter, located just above the detector at 79 K to measure the detector dark current (DC) in situ. Immediately preceding each flight, a suite of dark images is measured while the rocket is on the rail awaiting launch. These data are coadded to generate a pixel-wise template of the variations in DC containing negligible read noise. In addition, during each flight, the shutter is closed for approximately 50 s to obtain an in-flight dark measurement, albeit containing significant read noise contributions. The average DC is typically $0.5 e^- s^{-1}$ in unmasked pixels, comparable to the photocurrent induced from the ZL. In this measurement, the most important DC feature is the reproducible large scale structure across the array due to fabrication inhomogeneities in the detectors. The random alignment of array-scale DC structure and the wavelength distribution produces a bias in fitting the Ca II line depth if left unsubtracted. The rail DC template is therefore subtracted in the map domain before spectral analysis. An image of a typical DC template is shown in array coordinates in Figure 2. Bright features at the corners are caused by multiplexer glow and are masked, along with the ovular shaped feature toward the $x = 256$, $y = 128$ location.

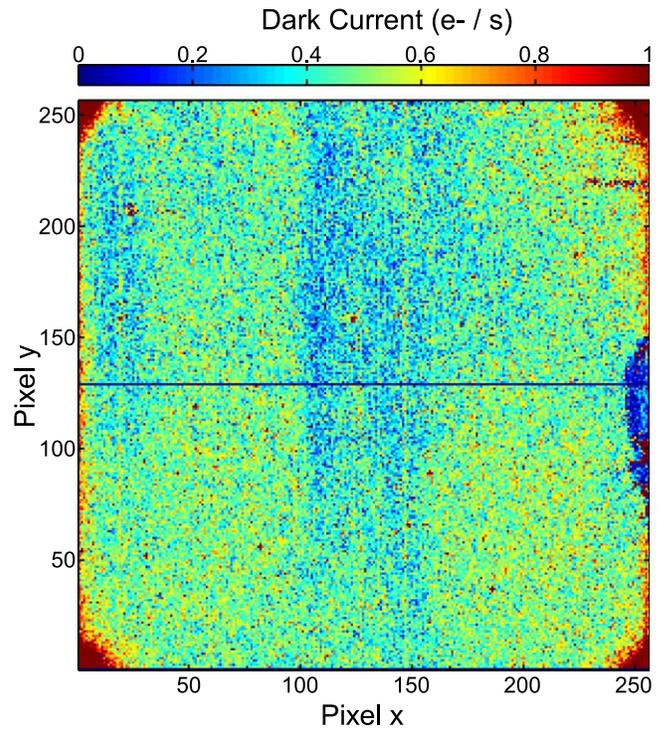


Figure 2. NBS DC template image in array coordinates.

5.2. Step Removal

The detector readout system uses two separate boards to read individual halves of the array. Drifts in the independent amplifier chains of the two channels can introduce different offsets on either side of the array. Since the NBS measurement quantifies the depth of an absorption line, it is not sensitive to arbitrary DC offsets. However, since the radial dispersion of the Ca II feature is not perfectly aligned with the midplane of the detector array, averaging across the entire FOV would introduce spurious inferred depth of the absorption feature. Therefore, we extract a spectrum independently on each half of the array, calculate the offset between the two spectra and remove the difference. For each field, spectra for each half of the array are extracted independently.

5.3. Flat Field

The flat-field response of the NBS was measured before and after each flight campaign in the laboratory. The measurement technique is discussed in detail in Zemcov et al. (2013) and entails coupling the NBS aperture into an integrating sphere enclosed in a vacuum chamber. Broadband light is coupled to the integrating sphere via fiber optic cable and the light intensity can be varied as desired. The flat field is constructed by coadding dozens of dark-subtracted exposures together and normalizing the response to the mean of all pixels used in spectral analysis. The measurement is repeated at three different light levels spanning an order of magnitude in photocurrent. An example of a flat-field matrix is shown in Figure 3. The structure in the flat-field matrix comes from a combination of intrinsic quantum efficiency variation in the detector array along with reflections and varied illumination in the optical chain. Because the optics were disassembled and reassembled between flights, we use a unique flat-field template for each flight.

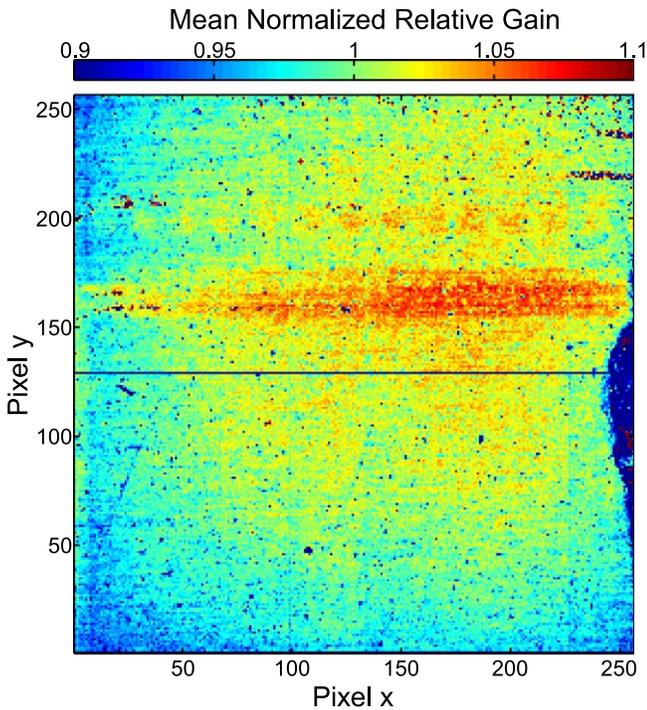


Figure 3. Flat-field gain matrix in array coordinates. The color scale is normalized by the mean across the array. No masking is included in the figure.

5.4. Pixel Masking

Errant pixels are flagged and excluded from the analysis based on a range of criteria as follows.

1. Hot and dead pixels are rejected. These are identified as extreme statistical outliers in DC measurements. The specific PICNIC chip in the NBS has a thin arc-like defect ~ 10 pixels in radius toward the edge of the array, which is masked here. In total, $\sim 3\%$ of pixels are removed at this stage. This mask is used in common for all fields in a given flight.
2. For each field, a variance estimator map is generated from the statistics of the best line fit in determining the estimated photocurrent. Statistical outliers which deviate from the mean in excess of 5σ are rejected. These account for typically $\sim 1.5\%$ of the array, including an overlap in population with the previous condition.
3. The corners of the array are masked to avoid contamination from a spurious signal originating from self-emission from the detector's multiplexor at the corner of each quadrant. The regions along the interface of the four quadrants of the array are masked as well. The effect being mitigated is visible in the DC image in Figure 2.
4. Pixels with extreme values in the flat-field matrix are excluded (greater than 5σ from the mean).

5.5. Calibration

The absolute spectrophotometric calibration of the NBS is obtained through a suite of laboratory measurements in collaboration with the National Institute of Standards and Technology. In particular, their SIRCUS laser facility (Brown et al. 2006) provides an intensity stabilized monochromatic source with negligible intrinsic linewidth for our purposes. The

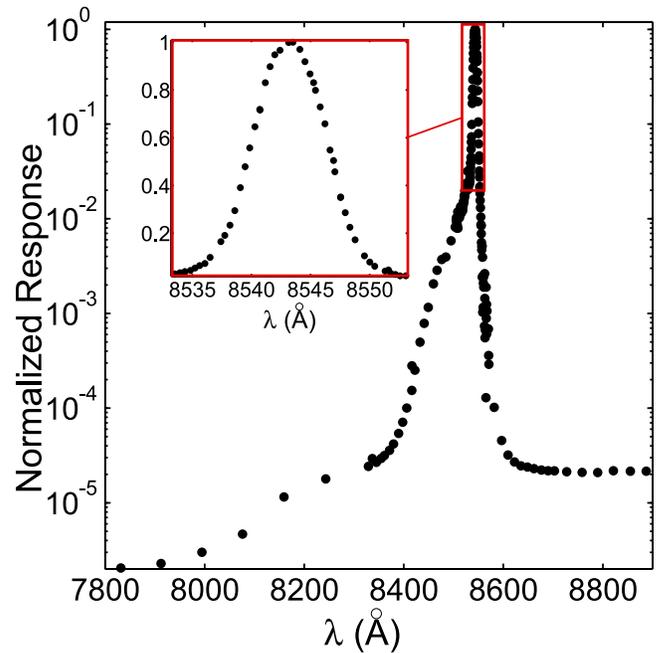


Figure 4. NBS spectral response function measured with the SIRCUS laser facility for a single pixel. The main band is shown on a linear scale in the inset. The out-of-band response is shown in the full plot with a factor of a million in dynamic range. This function corresponds to $\Lambda_{163,168}(\lambda)$ in Equation (1).

central wavelength of the laser is tunable and can be scanned across the NBS band. This source is coupled to the NBS aperture through an integrating sphere, with a series of absolutely calibrated radiometers (to 0.2% accuracy) and monitor detectors in the optical chain. A measurement of the spectral response function of each pixel is obtained with a dynamic range of 10^6 by dramatically increasing the intensity of the light in the sphere when probing wavelengths adjacent to the band. Figure 4 shows the measurement on a single pixel over a range of 1000 Å.

The spectral response was measured on five separate occasions, spanning numerous intermittent thermal cycles, rocket flights, and mechanical adjustments to the payload. A weighted average across all measurements provides a global calibration factor of $CF = 631 \pm 15 \text{ nW m}^{-2} \text{ sr}^{-1} / \text{e}^{-} \text{ s}^{-1}$, i.e., reproducible to 2.4%.

5.6. Astrometry

Astrometric registration is carried out in a two step process. First, an initial pointing solution is determined from the attitude control system, which specifies a mapping for each flight from pitch, yaw, and roll; to R.A., decl., and parallactic angle. An offset in all three parameters is then fit for using cross-identified stars in the Two Micron All Sky Survey all-sky catalog (Skrutskie et al. 2006). Radial distortion across the FOV is accounted for using detailed optical ray tracing simulations of the instrument, and are validated against star positions across the FOV.

6. 2D Component Modeling

For tipped filter spectroscopy, the raw measurement consists of an image of the sky in which each pixel has a slightly different bandpass (as depicted in Figure 1). In the limit where the ZL illumination is dominant and uniform across the FOV,

Table 2
Model Parameter Definitions and Background Used in the Analysis

Parameter	Description	Component	Ancillary Model	Float?
A_{ZL}	Amplitude parameter	ZL	...	Yes
$G_{ZL,x,y}$	Spatial gradient	ZL	Kelsall et al. (1998)	No
$F_{\lambda,ZL}$	Spectral template	ZL	Korngut et al. (2013)	No
A_{DGL}	Continuum amplitude	DGL	Arai et al. (2015)	No
$G_{DGL,x,y}$	Spatial gradient	DGL	Schlegel et al. (1998)	No
$F_{\lambda,DGL}$	Spectrum	DGL	Lehtinen & Mattila (2013)	No
A_{BISL}	Continuum amplitude	BISL	Monet et al. (2003)	No
$G_{BISL,x,y}$	Stellar positions	BISL	Monet et al. (2003)	No
$F_{\lambda,BISL}$	Stellar Ca II	BISL	Lehtinen & Mattila (2013) Vanhollebeke et al. (2009)	No
A_{FISL}	Continuum amplitude	FISL	Vanhollebeke et al. (2009)	No
$F_{\lambda,FISL}$	Faint unresolved stars	FISL	Lehtinen & Mattila (2013) Vanhollebeke et al. (2009)	No
C	Featureless offset	DC AGL EBL	...	Yes

the image produced by the NBS would appear as an azimuthally symmetric torus centered around the peak wavelength. However, in practice there are other components to the total sky signal that have spatial structure that produce a nonzero spurious ZL signal through the fitting process. In fact, in the NBS' $8^{\circ}5 \times 8^{\circ}5$ FOV, the ZL itself can have non-negligible gradients, particularly at lower ecliptic latitudes.

To make the most accurate determination of the ZL intensity from the NBS data set, we model each field in two dimensions, relying on ancillary data for the other components. The model we generate for the measured brightness of each pixel x, y in NBS detector array coordinates can be expressed as a sum of integrals given by

$$\begin{aligned}
 \lambda_{\Lambda_{x,y}} &= A_{ZL} G_{ZL,x,y} \int d\lambda \Lambda_{x,y}(\lambda) F_{\lambda,ZL}(\lambda) \\
 &+ A_{DGL} G_{DGL,x,y} \int d\lambda \Lambda_{x,y}(\lambda) F_{\lambda,DGL}(\lambda) \\
 &+ A_{BISL} G_{BISL,x,y} \int d\lambda \Lambda_{x,y}(\lambda) F_{\lambda,BISL}(\lambda) \\
 &+ A_{FISL} \int d\lambda \Lambda_{x,y}(\lambda) F_{\lambda,FISL}(\lambda) + C, \quad (1)
 \end{aligned}$$

where $\Lambda_{x,y}$ is the spectral response function of pixel (x, y) , $G_{i,x,y}$ encompasses the spatial variation of component i across the FOV, $F_{\lambda,i}$ is the narrowband spectrum of each component, A_i is an amplitude normalization parameter and C is a spectrally flat offset, which can include emission from residual airglow (AGL) and the EBL, which are both spectrally smooth in this region. The offset C can also include electrical effects within the detector and readout system, which is why it is not shown in a bandwidth integral.

To quantify the impact they have on the measurement, the characteristics of each component must be understood

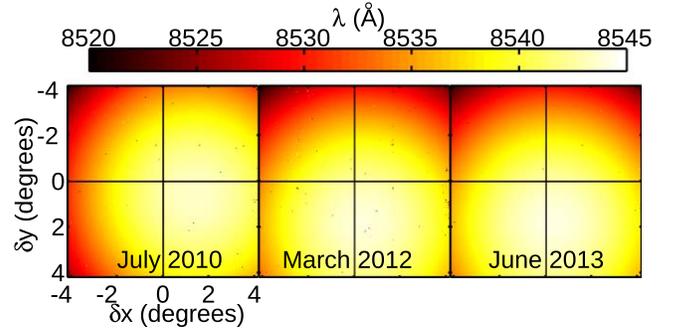


Figure 5. Wavelength calibration maps for the detector array used in analysis of each of the three flights. The values displayed in each pixel here correspond to the central wavelengths of $\Lambda_{x,y}$ in Equation (1)

thoroughly. Sections 6.1 and 6.3 detail the assumptions in their modeling and Section 8 describes the propagation of their uncertainties. A summary of the parameters appearing in Equation (1) can be found in Table 2. Due to changes in the instrument configuration between flights, consisting mainly of a rotation of the relative alignment of the tip in the band defining filter and the detector array, the values of $\Lambda_{x,y}$ are unique for each pixel in each flight. The central wavelengths, as mapped to the array for all cases considered, are given in Figure 5. As discussed in Section 7, the only parameters considered free in Equation (1) are A_{ZL} and C , all other parameters are constrained by external data or models.

6.1. ISL

Galactic stars contribute significant flux to the measured Ca II signal. With coarse $2'$ pixels, the NBS has limited power to detect and mask stars individually, as each pixel contains many sources. Unlike the EBL, which is sourced from all redshifts, the spectra of the local stellar population adds

coherently and therefore contributes to the inferred depth of the Ca II line. Ideally, we would rely on deep ancillary star catalogs in each field to mask the images aggressively and remove stellar contamination directly. However, with the limited spatial resolution of $2'$, masking NBS data to the necessary depth would result in an intolerable loss of pixels. We therefore mask only to moderate depth, defined by magnitude M_{cut} , and rely on modeling and ancillary data to account for the remaining surface brightness below that threshold. For stars brighter than M_{cut} (BISL), we rely on an ancillary all-sky catalog at $\lambda = 880$ nm to generate pixel masks. For the aggregate faint stellar population (FISL), we rely on models of the Galaxy. The implementation of each is described in detail in the following subsections.

6.1.1. Bright Stars

For this study, we use the catalog produced by the USNO-B2 Digital Sky Survey (DSS) (Monet et al. 2003), which includes an NIR band centered at $\lambda = 880$ nm. While the wavelength difference and resolution between these instruments is less than ideal, it is the closest all-sky catalog publicly available, and we account for the minor wavelength difference through simulations.

Detailed knowledge of the effective point-spread function (PSF) is essential for an accurate accounting of the stellar foreground. The average PSF is measured in each flight independently by stacking on DSS star positions with $7 < M_{AB} < 9$. As the NBS design under-samples the PSF significantly, the stack is done on a sub-pixel grid, applying the technique implemented in Symons et al. (2021).

The star masking algorithm we apply is characterized by two parameters, an AB cutoff magnitude M_{cut} and a flux threshold parameter t . Using the measured PSF along with fluxes and positions from the DSS catalog, model stellar maps for sources brighter than M_{cut} in each field are generated. The maps are initially generated on a pixel scale four times finer than the NBS native resolution ($30''$ pixels) to account for the sub-pixel centroiding of sources. They are then interpolated onto the $2'$ grid. Pixels in the model maps with values brighter than t are masked in spectral extraction. This technique naturally removes a larger region around brighter stars.

6.1.2. Faint Stars

To account for the integrated emission from stars below the mask threshold, we rely on the Galactic stellar population code TRILEGAL (Vanhollebeke et al. 2009). This code is run for the CIBER target fields to generate statistically accurate simulated stellar catalogs down to $M_{AB} = 26$. The simulation calculates both the flux observed using the CIBER NBS filter as well as the DSS-i2 filter. Simulated noiseless observations of stellar fields are produced for both filters by randomly populating the stars across the NBS FOV using the appropriate PSF model.

The simulated NBS maps are then masked using an identical algorithm to the data, removing all pixels that appear in the simulated NBS map generated from the TRILEGAL-based DSS $M_{AB} < M_{\text{cut}}$ catalog above t . The FISL is taken to be a uniformly illuminating source with an amplitude set by the mean of the remaining pixels in the simulated TRILEGAL map.

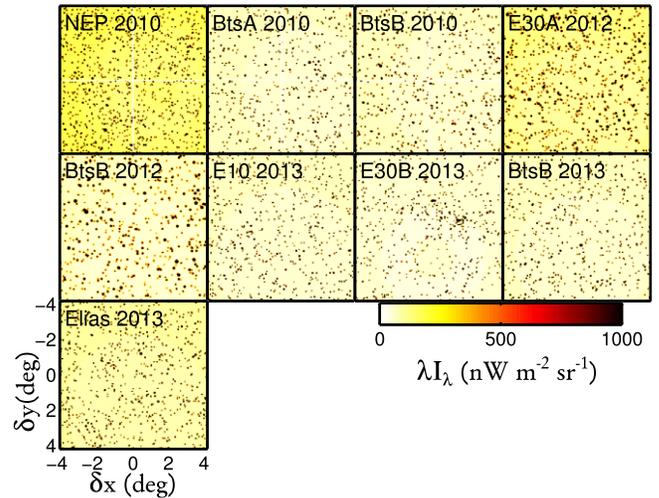


Figure 6. Template images of the integrated stellar light corresponding to the sum of $G_{\text{BISL},x,y} \int d\lambda \Lambda_{x,y}(\lambda) F_{\lambda,\text{BISL}}(\lambda) + \int d\lambda \Lambda_{x,y}(\lambda) F_{\lambda,\text{FISL}}(\lambda)$ in Equation (1). Individual sources are generated from the DSS catalog positions and fluxes, determined NBS astrometry, and a model of the NBS PSF. The faint background is generated from the TRILEGAL model, and shown as observed by the NBS wavelength response assuming Solar Ca II absorption.

The final template ISL maps used in the fit are generated as the sum of the simulated DSS map and a uniform offset with an amplitude determined by the mean of the TRILEGAL FISL map multiplied by the response function-convolved Ca II absorption line with solar depth (discussed in the following section). These maps are shown in Figure 6.

6.1.3. Ca II in the ISL

Since the ISL from the Milky Way arises entirely from sources at $z \sim 0$, spectral features, including the Ca II line of interest will add coherently in the aggregate signal. The ISL is composed of the entire stellar population, with a range of Ca II depths, which could vary from location to location in the Galactic disk. Unfortunately, a high resolution ISL model in the appropriate region is not available in the current literature. At moderate resolution, Lehtinen & Mattila (2013) have compiled a global data-based model at a resolution of $\delta\lambda = 10$ Å. At this resolution (approximately 50% lower than the NBS), the Ca II line is marginally resolved. In Figure 7, we show the depth of the line as a function of Galactic latitude. While a clear trend is present in the model close to the Galactic plane, for the fields included in this study (marked in red), the effect is negligible at $\sim 0.01\%$. Also shown in Figure 7 is the high resolution solar spectrum downgraded in resolution assuming an FWHM = 10 Å Gaussian response function along side the average ISL spectrum from Lehtinen & Mattila (2013). As will be discussed in Section 8, we take the uncertainty in residual FISL amplitude from the TRILEGAL model to be 30%. For purposes of the accuracy presented in this work, the 30% uncertainty dominates over the uncertainty in the ISL Ca II depth. Additionally, we provide a test that allows us to bound the effect self-consistently using the NBS data.

6.1.4. Test of the BISL Ca II Line to Continuum

While it is impossible to independently assess the total residual ISL from the NBS data as it is degenerate with the ZL signature, one can assess the accuracy of the BISL model through differential measurements. The star masking algorithm

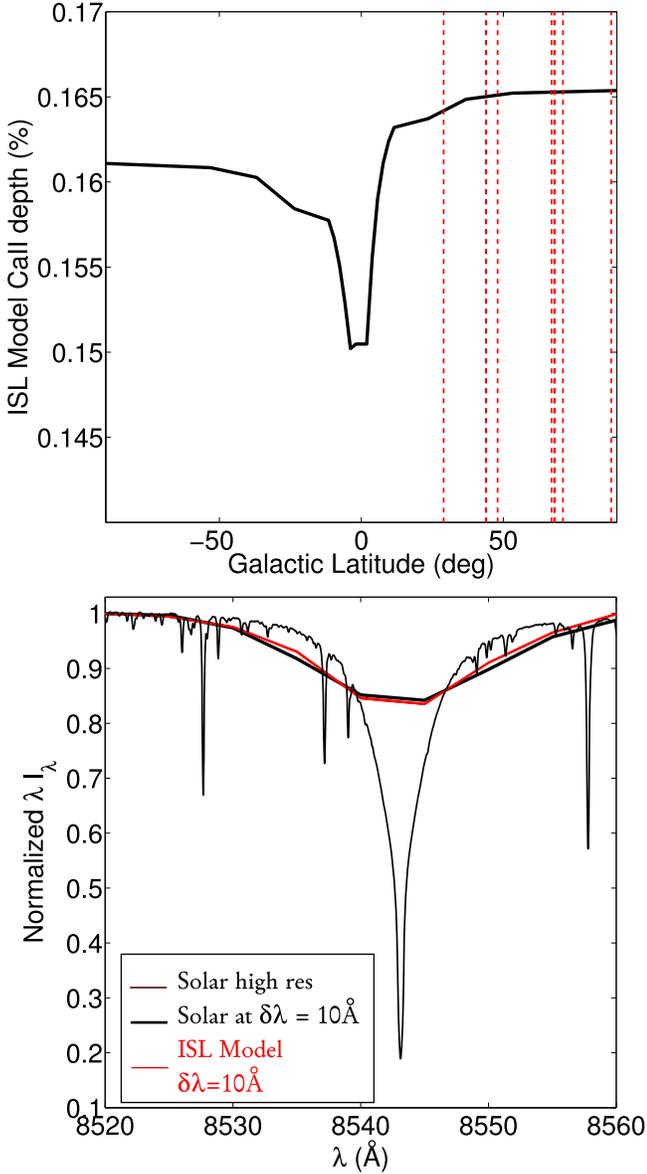


Figure 7. Top: depth of Ca II in the Lehtinen & Mattila (2013) ISL model as a function of Galactic latitude. Locations of fields in this paper are shown as vertical red dashed lines. Bottom: comparison of the Lehtinen & Mattila (2013) ISL model and solar spectra near the Ca II line. The solar spectrum is shown both at its native resolution (thin black) and downgraded to match the ISL model at $\delta\lambda = 10 \text{ \AA}$ (thick black).

determines the level of residual ISL, subject to the choice of M_{cut} and t . We define a test as follows and carry it out for a range of M_{cut} and t for all the target fields.

1. A star mask is generated using the algorithm described in Section 6.1.2 for an arbitrary M_{cut} and t .
2. The mean intensity in the two-dimensional NBS data is calculated for the pixels remaining after star and instrument masking. The intensity below a masking threshold can be expressed as

$$\lambda_{\lambda, \text{data, total}}(M_{\text{cut}}, t) = \lambda_{\lambda, \text{ISL}}(M_{\text{cut}}, t) + \sum_i \lambda_{\lambda, \text{data}, i}, \quad (2)$$

where i can be any other source of signal other than ISL (ZL, DC, DGL etc.) and thus independent of M_{cut} and t .

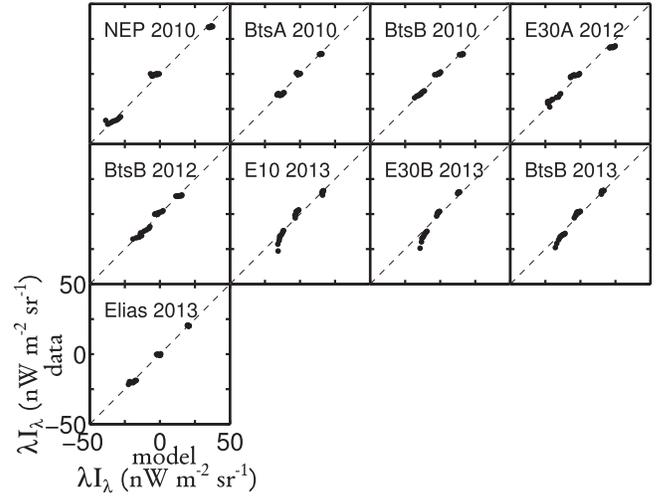


Figure 8. Stellar template and measurement consistency is tested in each field by varying the star mask and calculating the mean intensity in the remaining unmasked pixels. The mask is generated using knowledge of the absolute calibration, PSF, and astrometry combined with fluxes and positions from the ancillary star catalog. The model is generated from the TRILEGAL simulations and both assume Ca II absorption at a solar level. The dashed line shows unity correlation between data and model. The best-fit slope is 1.0 ± 0.1 .

3. Synthetic template images are made from TRILEGAL simulated catalogs in both the DSS-i2 and NBS filters assuming solar Ca II depth. These images include stars down to $M_{\text{AB}} = 26$. The appropriate NBS PSF is used for each field.
4. The mean in the simulated image is masked with the same values of M_{cut} and t . The quantity can be expressed as

$$\lambda_{\lambda, \text{model, total}}(M_{\text{cut}}, t) = \lambda_{\lambda, \text{model, ISL}}(M_{\text{cut}}, t), \quad (3)$$

as there is only one component included.

5. Taking a derivative with respect to M_{cut} and t in Equations (2) and (3) and equating the two, the expression

$$\frac{d\lambda_{\lambda, \text{data, total}}}{dM_{\text{cut}} dt} = \frac{d\lambda_{\lambda, \text{model, ISL}}}{dM_{\text{cut}} dt} \quad (4)$$

is valid in the limit that the model is a perfect description of the ISL.

In Figure 8 we show how the data and model in Equation (4) relate. Specifically, we plot the left-hand side of Equation (2) against the left side of Equation (3) for the range $10 \leq M_{\text{cut}} \leq 12$ and $5 \leq t \leq 100 \text{ nW m}^{-2} \text{ sr}^{-1}$. Since each field has different offsets from the other components, we subtract a mean of each curve. The dashed line is the case of the model being a perfect description of the ISL. This test can allow us to probe errors included in the ISL model, the absolute calibration, the Ca II absorption depth of the ISL, the astrometric solution and the extended PSF model. The measured slope of the correlation is 1.0 ± 0.1 averaged across all fields. One can interpret the relation as supporting the ISL having a solar Ca II depth to better than 10% accuracy.

The unity correlation builds good confidence in the quality of the BISL model, but does not help constrain the accuracy of the ISL models below the masking threshold. Ultimately, to quantify the uncertainty in our residual ISL amplitude and its effect on the ZL measurements, we rely on model accuracy tests in the literature, discussed in Section 8.

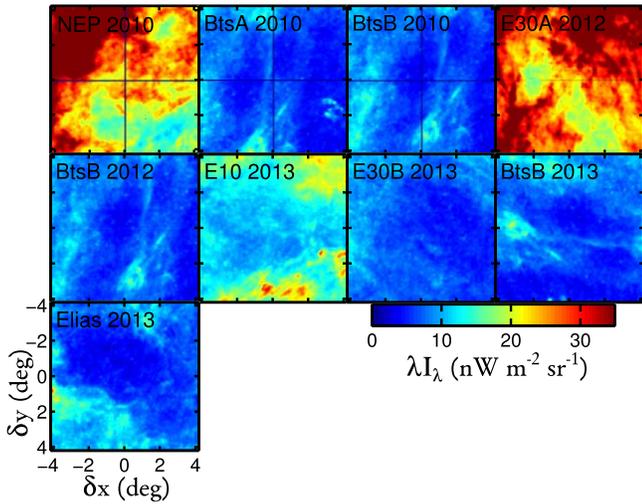


Figure 9. Template images of the DGL as it lands on the NBS array. The images correspond to $G_{\text{DGL},x,y}$ in Equation (1) and do not account for the Ca II absorption feature.

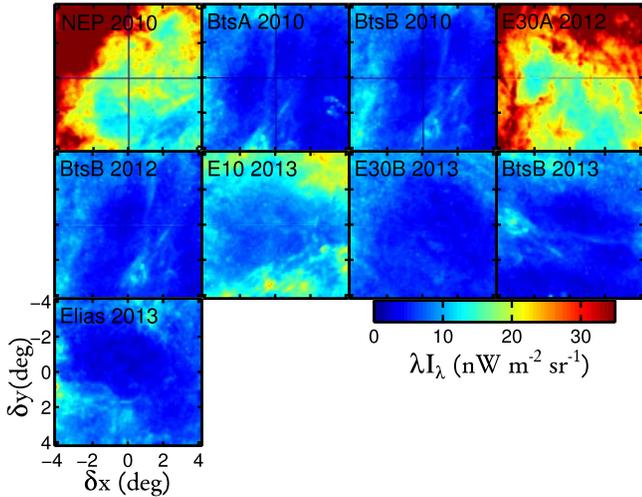


Figure 10. DGL distributions on the NBS FOV identical to Figure 9 after accounting for Ca II absorption features in the DGL. This quantity corresponds to $G_{\text{DGL},x,y} \int d\lambda \Lambda_{x,y}(\lambda) F_{\lambda, \text{DGL}}(\lambda)$.

6.2. DGL

DGL arises from the same scattering phenomena as the ZL, only on larger scales. In this case, the illuminating light is the Galactic radiation field and the scattering medium is interstellar dust. To estimate the continuum signal of DGL as it lands on the NBS FOV, for each field we interpolate the dust map of Schlegel et al. (1998) onto the astrometrically registered grid for the pointing in each field. It is then normalized to the appropriate continuum intensity using the scaling relation derived by Arai et al. (2015). These maps, corresponding to G_{DGL} in Equation (1) are shown in Figure 9. As is made evident by this figure, spurious alignment of intrinsic structure in the Galactic cirrus and the spectral response of each pixel on the array can produce a bias to the inferred ZL intensity from the Ca II absorption feature. By administering robust priors on the spatial distribution of the cirrus, this bias can be mitigated.

The case of DGL is further complicated by the fact that the interstellar radiation field also contains Fraunhofer lines, which are also scattered by the interstellar medium. Figure 10 shows

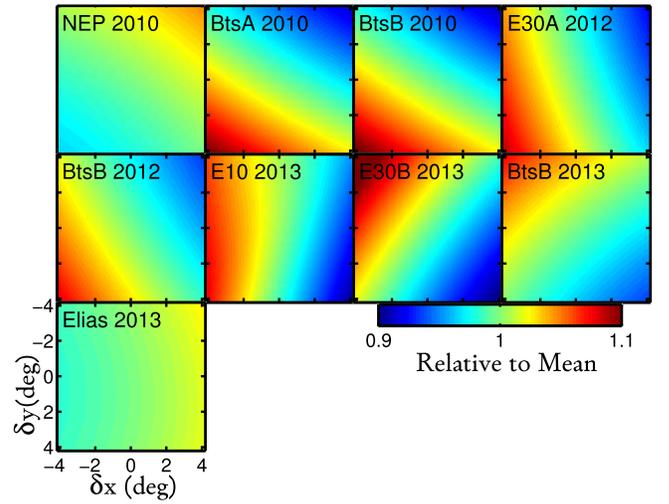


Figure 11. The gradient in ZL intensity across the NBS field of view as described by the Kelsall et al. (1998) model at $1.25 \mu\text{m}$. This is representative of the continuum only and does not account for the wavelength distribution of the NBS. All fields are normalized to their mean and shown on the same color scale.

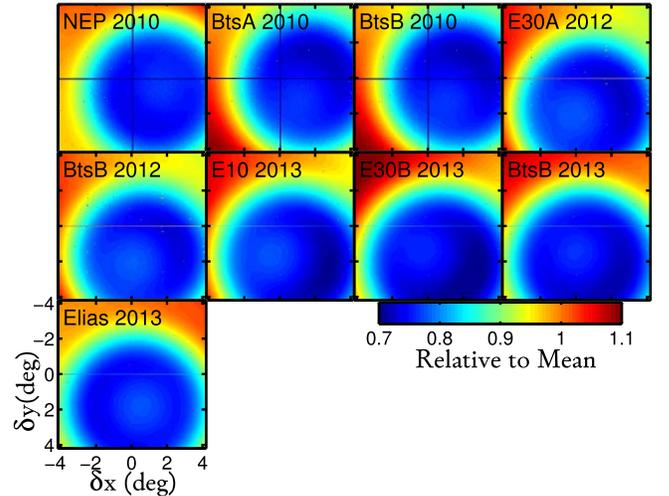


Figure 12. ZL spatial and spectral templates for each field as observed by the NBS. They are generated by multiplying the gradient shown in Figure 11 by the Ca II absorption line profile for a uniform illumination. All fields are normalized by the mean.

the modeled DGL distribution after accounting for intrinsic absorption, it is simply modeled using the spatial DGL template in Figure 9 multiplied by the 2D solar absorption template for Ca II. The model assumes solar depth in the DGL Ca II profile as it arises from a scattered ISL.

6.3. ZL

Because of the 8.5×8.5 instantaneous FOV of the NBS, and the desired level of accuracy, assuming a uniform ZL intensity can produce a $\sim 5\%$ error in the derived ZL amplitude. We use prior models of the spatial distribution of the ZL to reduce error from spatial gradients. Figure 11 shows ZL gradients computed from the Kelsall et al. (1998) model over the NBS FOV for each field. These gradients are normalized by the mean over the FOV. Figure 12 shows the effect these gradients have on the ideal Ca II absorption feature as shown on the solar spectrum in Korngut et al. (2013).

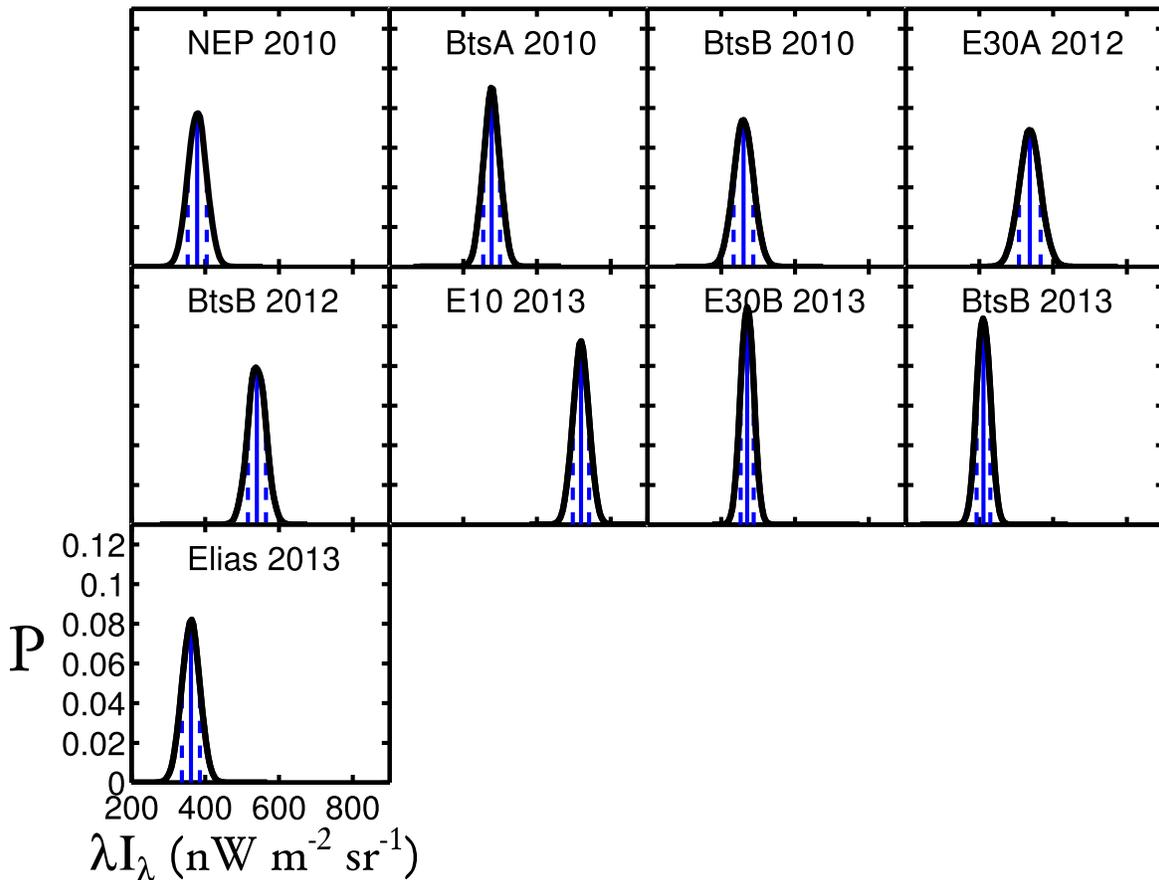


Figure 13. PDFs for the ZL continuum intensity parameter A_{ZL} at 8520 \AA after marginalizing over the spectrally smooth offset parameter C . Solid blue lines show the mean with the two dashed lines $\pm 1\sigma$. These distributions represent statistical sources of error only.

7. Model Fits

After considering all of the effects discussed in Section 6, the models are fit to the data in each field using the algorithm described below. Before fitting, the NBS images are processed following the procedures described in Section 5. We fit the processed images as follows.

1. We generate a two-dimensional template consisting of all fixed components including the DGL, BISL, and FISL. There are no free parameters in these products, as everything is generated using ancillary data and empirically determined instrument characteristics.
2. We add a ZL template to the model. This consists of the ideal Ca II absorption profile (Kornгут et al. 2013) mapped to the NBS wavelength response after accounting for the gradient across the FOV determined by the ancillary ZL model normalized by the mean. The ZL template has a free normalization A_{ZL} .
3. We add a free spectrally flat offset C to account for the EBL.
4. Both the data and model are masked using the pixel masking criteria described in Section 5 and the stellar masking described in Section 6.1.
5. One-dimensional spectra are extracted for both the model and data and the reduced χ^2 statistic is computed. The statistical errors on the one-dimensional spectra are computed from the rms variation within an isowavelength bin divided by the square root of the number of pixels used.

We vary and fit the ZL amplitude parameter A_{ZL} and the offset C . Because the spectral shape $F_{\lambda,ZL}$ is externally constrained by the solar spectrum, A_{ZL} encompasses the absolute intensity of the ZL at a given line of sight, which is the focus of our study. After the two-dimensional χ^2 distribution is generated, the offset parameter is marginalized over to produce the probability density functions (PDFs) shown in Figure 13. The PDFs are well behaved with single prominent peaks. The 1σ statistical error bars presented in this paper are taken from the width of these PDFs, which have typical values of $\sim 23 \text{ nW m}^{-2} \text{ sr}^{-1}$. We note that the level of statistical uncertainty is entirely consistent with the values presented in Kornгут et al. (2013), which were determined by Monte Carlo simulations using realizations of measured laboratory noise. The measured spectra in 1D are shown along with the best fit models in Figure 14. The error bars in the 1D spectra are determined by the rms of the pixels in an isowavelength bin divided by the square root of the number of pixels.

8. Systematic Errors

In addition to the statistical errors determined in Section 7, a number of additional systematics must be accounted for.

8.1. Instrument Systematics

8.1.1. Spectral Correction

The shortest wavelength probed by the DIRBE instrument, upon which the Kelsall and Wright models are based, is

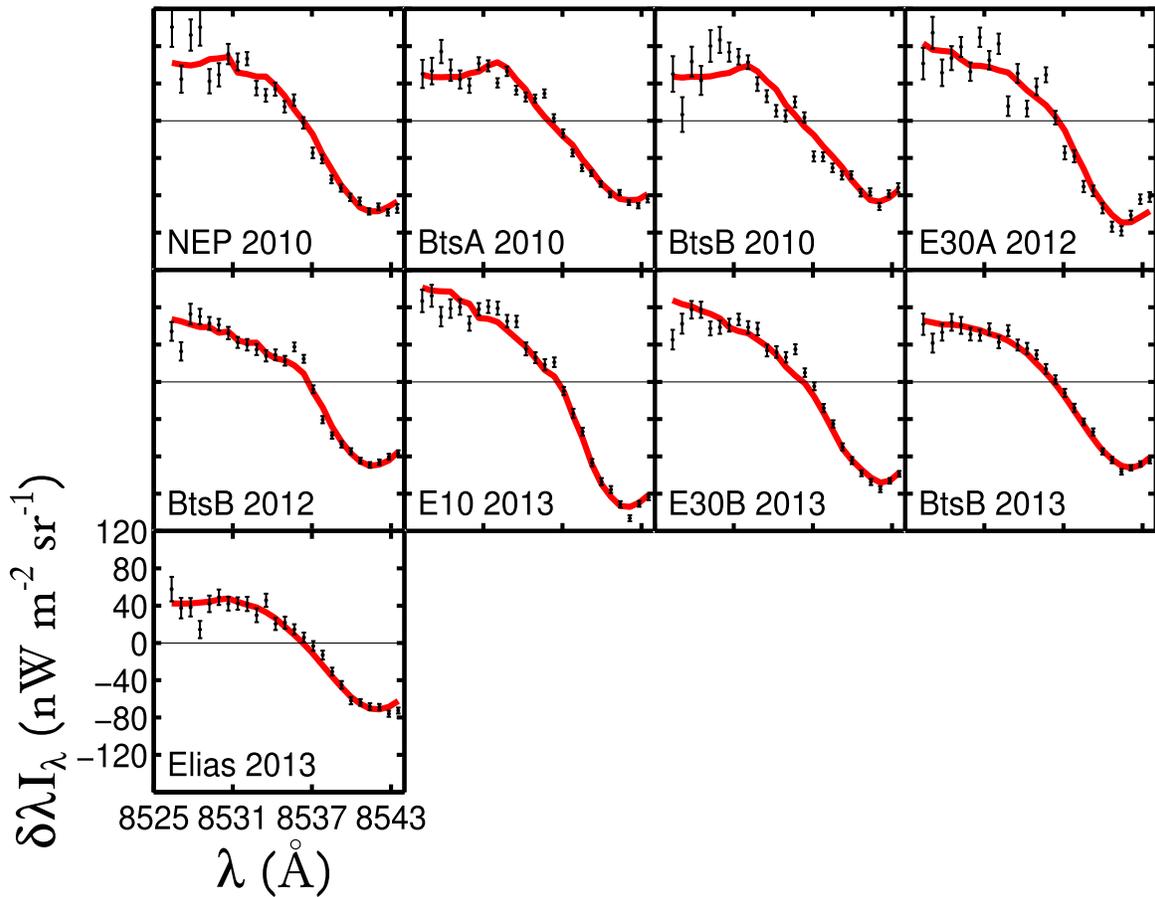


Figure 14. One-dimensional measured spectra (black data points) with best-fit models (red curves) for all fields. To show the variation in line depth, all axes are matched and a mean has been subtracted from all spectra. The models are fit with only a ZL amplitude and constant offset as free parameters. The variation in line profile between fields is due to structure in the DGL and the gradient in ZL at each location, constrained entirely by external information. The DGL and ZL gradients are included in the red curves.

12500 Å. Therefore, to compare the inferred NBS continuum measurements at 8520 Å with the ancillary models, a spectral correction is needed. To do this, we rely on $\frac{\lambda}{\Delta\lambda} \sim 20$ measurements of the ZL continuum spectrum made by the CIBER LRS. As the LRS is co-mounted with the NBS on the rocket, the template is generated using the same fields observed at the same epochs. Construction of the template is given in Matsuura et al. (2017). The measured ratio between the two wavelengths for ZL is $\frac{\lambda_{\lambda,ZL}(\lambda = 8520 \text{ Å})}{\lambda_{\lambda,ZL}(\lambda = 12500 \text{ Å})} = 1.25 \pm 0.1$. It should be noted that this ratio is substantially smaller for the solar spectrum $\frac{\lambda_{\lambda,Solar}(\lambda = 8542 \text{ Å})}{\lambda_{\lambda,Solar}(\lambda = 12500 \text{ Å})} = 1.5$. This discrepancy is accounted for by spectral reddening from the IPD (Tsumura et al. 2013). The inferred NBS values for each field are divided by this factor when comparing to DIRBE model predictions.

8.1.2. Calibration Error

The absolute calibration factor used to convert an observed photocurrent to a physical intensity relies on the laboratory measured conversion (see Section 5). Laboratory measurements have shown reproducibility within 2.5%.

8.1.3. DC

To quantify the error introduced by DC subtraction, we compare the low-noise rail DC template image to the in-flight

image taken with the cold shutter closed during the 2013 flight. This represents a worst-case condition, as the focal plane temperature stability during this flight was substantially worse than the previous flights. The instrument included an active temperature control system that regulated the focal plane temperature. During the 2009 and 2012 flights, the system worked nominally and the focal plane was regulated within an rms of $\pm 15 \mu\text{K}$. Due to the base temperature in the 2013 flight operating outside the dynamic range of the control unit, the 2013 flight was conducted with only passive thermal stability. A pixel-wise correlation of the DC rail template and flight measurement show a linear trend with a slope of 0.4. We pass a residual map of the DC template after subtracting a scaled down image through the Ca II fitting pipeline to quantify the amplitude of a systematic error. This is taken to apply randomly to all fields with an amplitude of $1\sigma = \pm 17 \text{ nW m}^{-2} \text{ sr}^{-1}$, referred to as the ZL continuum intensity at 8520 Å.

8.1.4. Flat Field

The accuracy of the flat-field correction is determined by fitting a Ca II line response to the ratio of flat fields obtained at different intensity levels in the laboratory. Using this technique, we estimate the error introduced by the flat field to be a multiplicative factor of 0.3%, far subdominant to the other multiplicative errors such as the calibration factor and the

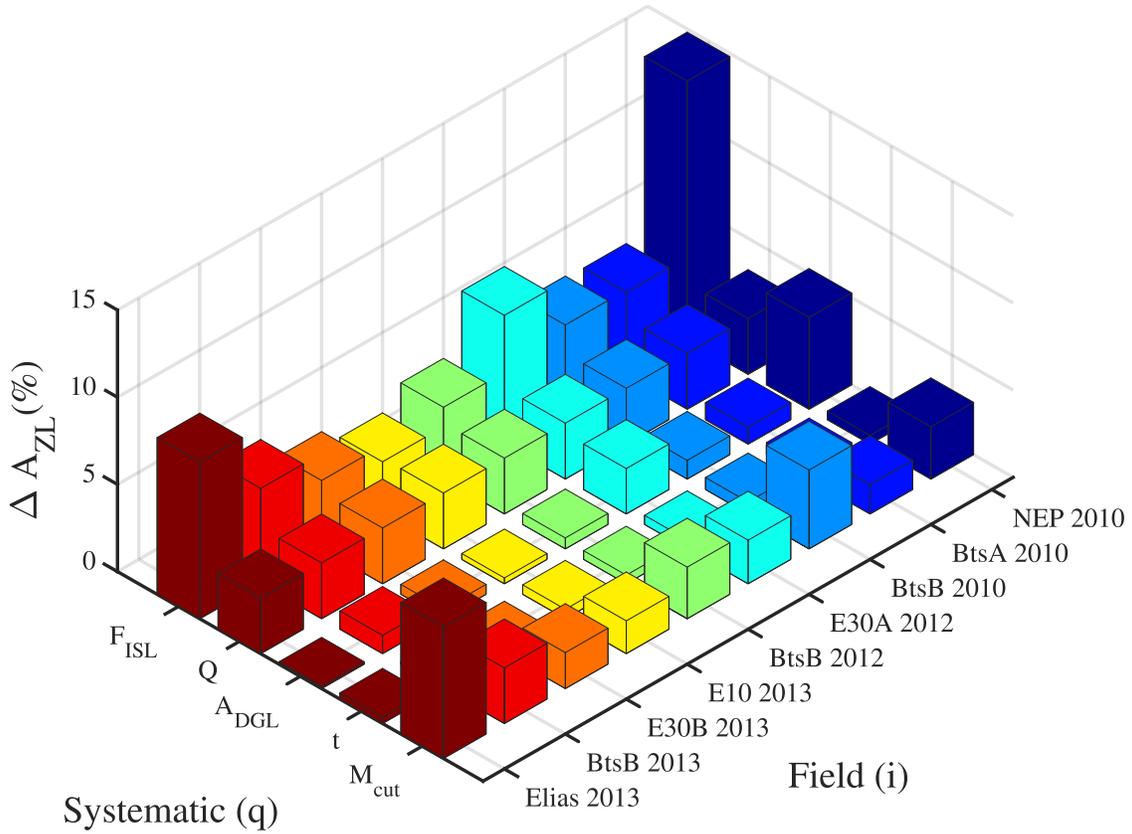


Figure 15. Variation in the estimate of A_{ZL} attributed to individual systematic errors for each field. For simplicity, we define the parameter Q to be the product of the calibration and wavelength extrapolation systematics. Due to the variation in stellar properties, dust content and ZL amplitude in each location, the breakdown of systematic contributions is unique for each field.

Table 3

Parameter Ranges Explored in the Systematic Error Analysis

Parameter	Low	High	Units
M_{cut}	12	10	m_{AB}
t	5	100	$\text{nW m}^{-2} \text{sr}^{-1}$
δA_{DGL}	0.7	1.3	...
δA_{FISL}	0.7	1.3	...
Cal	618	650	$\text{nW m}^{-2} \text{sr}^{-1}$ $/(\text{e}^{-} \text{s}^{-1})$
$\frac{\lambda_{A,ZL}(\lambda = 8520 \text{ \AA})}{\lambda_{A,ZL}(\lambda = 12500 \text{ \AA})}$	1.24	1.26	...
FF	0.997	1.003	...

Note. For all parameters, a uniform distribution spanned by this range is explored.

spectral correction. This uncertainty level is consistent with an estimate produced by measuring the Ca II signal in solar light coupled to the laboratory by fiber and comparing to precise archival solar spectra (Korngut et al. 2013).

8.2. Modeled Astrophysical Systematics

8.2.1. DGL

The scaling of the Schlegel et al. (1998) maps to the NIR (which sets A_{DGL}) implemented in this analysis is set by the empirically determined relation of Arai et al. (2015) from CIBER LRS data. The relation has a 30% error associated with it, which directly propagates to the modeled DGL component.

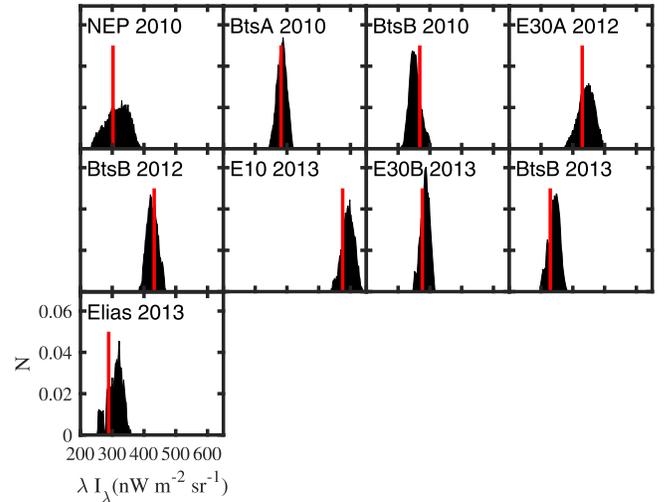


Figure 16. Histograms of A_{ZL} for each field's allowed parameter space of systematic errors. The histograms are normalized by the number of permutations explored. The red vertical line denotes the a priori assumed nominal set of parameters, which is different from the most visited value in some cases.

8.2.2. Bright ISL

As discussed in detail in Section 6.1.4, the parameterization of the DSS-based ISL model with M_{cut} and t encompasses the accuracy of the ISL model along with the measured instrument parameters, which go into the generation of synthetic star maps such as the extended PSF, the distortion field, and astrometric

solution. For a perfect model with zero systematic error, a measurement of the ZL intensity should be constant with any choice of M_{cut} and t . For less aggressive mask cuts, the ISL makes up a higher fraction of the total signal. For very aggressive cuts, too few pixels remain for spectral extraction.

8.2.3. Faint ISL

The amplitude of the ISL at magnitudes fainter than the masking threshold is based on the TRILEGAL star count model and an assumed solar Ca II absorption depth. Comparisons of the output of this model and numerous source count measurements agree to within $\pm 30\%$ (Vanhollebeke et al. 2009). This uncertainty is propagated directly to our measurements.

8.3. Error Propagation

Because the chosen celestial field locations span a large range of Galactic and ecliptic latitudes, the component breakdown of errors is unique for each target. Other systematic errors, such as the instrumental calibration factor, affect our measurements multiplicatively and systematically push all field measurements up and down together. It is therefore necessary to understand the interplay between the various effects on a field-by-field basis. Consequently, we calculate the combined systematic and statistical errors uniquely in each field.

To quantitatively illustrate the complex interaction of the systematic errors in each field, it is useful to define a parameter

$$\Delta A_{ZL,q,i} = \frac{A_{ZL,q_{\text{max},i}} - A_{ZL,q_{\text{min},i}}}{2A_{ZL,q_{\text{nominal},i}}}, \quad (5)$$

where q represents a given systematic error contribution and i represents the target field. To compute $\Delta A_{ZL,q,i}$, we fix all systematic errors other than q to their a priori assumed nominal values, and calculate $A_{ZL,q_{\text{max},i}}$ and $A_{ZL,q_{\text{min},i}}$, which are the best-fit ZL amplitudes under the assumptions that systematic q is at its maximum and minimum value within an allowed range, respectively. Figure 15 displays $\Delta A_{ZL,q,i}$ for each value of q and i , where the allowed ranges of systematics are given in Table 3.

While ΔA_{ZL} is useful in illustrating the extreme values allowed by isolated effects, to obtain a full understanding of allowed values of A_{ZL} it is necessary to carry out the entire analysis described in Section 7 under every permutation of systematic error parameters. To do this, we explore a grid of 2505 discrete permutations of the allowed error contributions, calculating A_{ZL} at each point for each field. The histograms of all outcomes of A_{ZL} are shown in Figure 16 after normalizing by the total number of permutations.

The varied shapes of the distributions reflect the characteristics of each field. In locations that have a large contribution of DGL and ISL compared to the total signal such as NEP, the distribution is wide and asymmetric. Regions that are dominated by ZL, such as Elat 30B, have well-defined peaks in the distribution.

9. Model Comparisons

As discussed in the introduction, nearly all NIR EBL absolute spectrophotometry measurements in the literature rely on ZL foreground subtraction based on models generated from geometrical fits to the DIRBE data. In

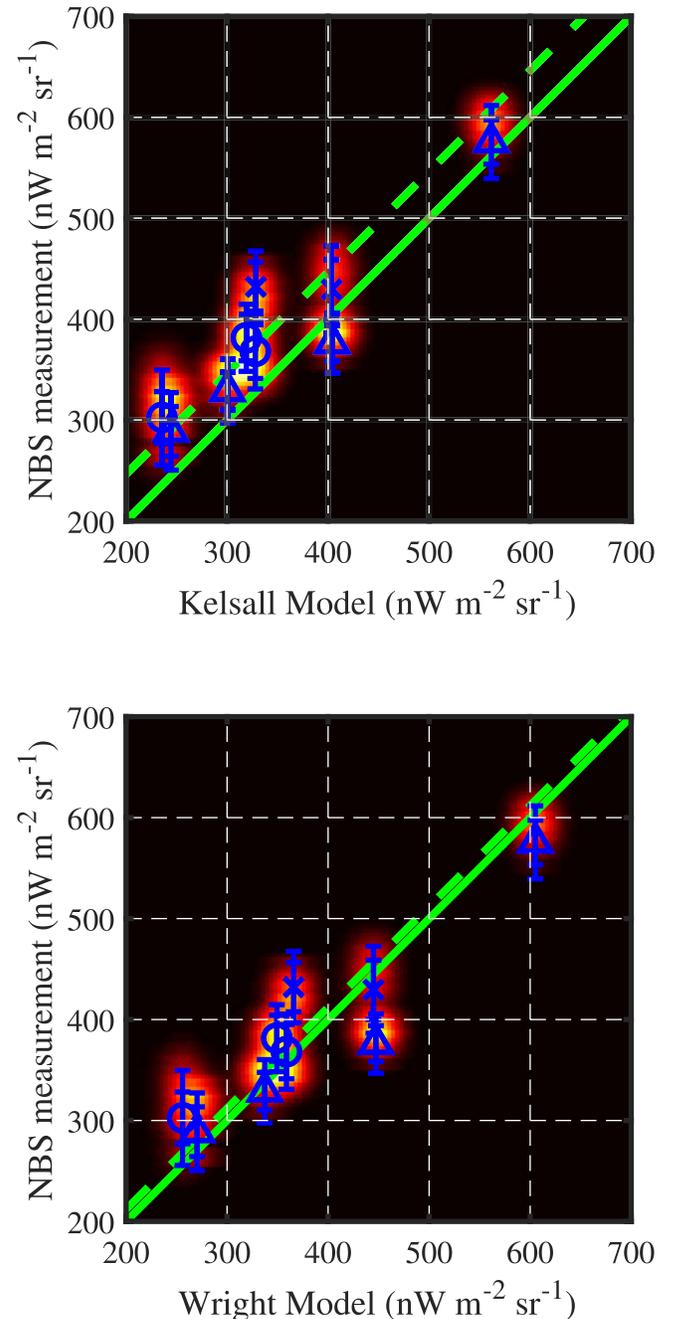


Figure 17. Comparison of the NBS ZL intensity measurements to the Kelsall (top) and Wright (bottom) models at 12500 Å. The color-scale errors are a two-dimensional visualization of the distributions given at each field from the systematic error analysis. Blue points show the amplitude estimates assuming nominal values for all systematic errors. The two sets of blue error bars, which represent the statistical only (inner), and combined statistical and systematic (outer). The blue marker type denotes the rocket flight in which the measurement was performed (2010 are circles, 2012 are x symbols and 2013 are triangles). The solid green line shows a unity correlation and the dashed green shows the unity correlation plus a best-fit offset for each model.

particular, measurements that report a higher level of EBL were generated using the model of Kelsall et al. (1998) and fainter estimates rely on Wright (2001). Because these two models bookend the range of reported EBL, we concentrate our analysis on applying NBS data as a test to the models and henceforth, a probe of whether a brighter or fainter EBL is favored.

Table 4
ZL Intensities at 1.25 μm Toward all Fields as Reported by the NBS Measurements Compared to the Two Models

Field	α (hr)	δ (deg)	Flight	NBS 1.25 μm ($\text{nW m}^{-2} \text{sr}^{-1}$) stat + sys	Kelsall 1.25 μm ($\text{nW m}^{-2} \text{sr}^{-1}$)	Wright 1.25 μm ($\text{nW m}^{-2} \text{sr}^{-1}$)
NEP	18.06	66.10	2010 Jul	302 ± 47	233	255
Bootes A	14.55	34.58	2010 Jul	382 ± 33	316	349
Bootes B	14.46	33.08	2010 Jul	368 ± 37	325	358
Elat 30A	15.77	09.29	2012 Mar	430 ± 43	402	444
Bootes B	14.45	33.02	2012 Mar	432 ± 35	327	365
Elat 10	12.69	08.32	2013 Jun	575 ± 36	551	605
Elat 30B	12.87	28.29	2013 Jun	376 ± 29	397	447
Bootes B	14.48	33.50	2013 Jun	329 ± 31	297	337
Elais-N1	16.19	54.34	2013 Jun	289 ± 38	242	270

In Figure 17 we show the correlation of the absolute ZL intensity inferred by the NBS to the Kelsall and Wright models after extrapolation to 12500 Å. In this plot, the blue points convey the estimates generated under nominal systematic error assumptions. The color scale encompasses the regions in which the blue points move around under the allowed range of uncertainty for all of the systematic errors. The vertical distribution of the color scale directly corresponds to the shapes of the histograms in Figure 16 and the horizontal distribution is assumed to have a Gaussian error $\sigma = 15 \text{ nW m}^{-2} \text{sr}^{-1}$, the error reported by Kelsall et al. (1998). The numerical values for the measurements are given in Table 4.

To assess how well each model describes the NBS measurement, we calculate a reduced χ^2 statistic at every explored location in parameter space. As shown in Figure 18, when no additional free parameters are allowed in the models, the χ^2 distributions look very different for the two cases.

In the case of the Kelsall model, the majority of the data points lie systematically higher than the model predictions, leading to a reduced χ^2 distribution that is very broad with a tail that extends all the way up to a value of 8 and a mean value of 3.5. For the Wright model, the distribution is more symmetrical with a mean value of 2.0. In this case, the data points are distributed both above and below the model predictions and the goodness of fit is limited by field-to-field scatter.

Also shown in Figure 18 are χ^2 distributions calculated under the simplest modification to the foreground model; the addition of a single free parameter in the form of a constant ZL offset. This modification represents a component of the ZL cloud, spheroidal in nature which surrounds the inner solar system and would evade detection in the Kelsall study as it does not modulate annually. Section 10.2 discusses physical explanations and supporting evidence for such a phenomenon. When this additional free parameter is included in computing χ^2 , the distribution of the modified Kelsall model changes dramatically. It displays a sharp symmetrical peak with a mean value of 1.5, coming down even after accounting for the additional degree of freedom. The Wright model distribution in this case is more symmetrical than without an offset, and the mean value reduces slightly to 1.9. The histograms of the best fit offset under all permutations of systematic errors for both the Kelsall and Wright models are given in Figure 19. The data suggest an offset from the Kelsall model with an amplitude of $46 \pm 19 \text{ nW m}^{-2} \text{sr}^{-1}$ at 12500 Å. The Wright model is consistent with zero, with a most likely value of $12 \pm 19 \text{ nW m}^{-2} \text{sr}^{-1}$ at 12500 Å.

10. Discussion

10.1. Model Testing and EBL Implications

We present new measurements of the ZL absolute intensity in the NIR through Fraunhofer absorption line spectroscopy. Through these measurements, we provide a test of the two ZL models most heavily cited in absolute NIR spectrophotometric measurements. After accounting for the interaction between statistical and systematic errors, we find the data favor an absolute ZL intensity that is somewhat brighter than predicted by the Kelsall model. The total observed intensity is closer to the Wright model, but with additional field-to-field scatter.

The offset distributions in Figure 19 can be loosely interpreted as residual ZL that would be falsely interpreted as EBL in an absolute measurement. The Wright model distribution has a mean consistent with zero within 1σ , whereas the Kelsall model distribution is 2.4σ above zero. The widths of these distributions limit the confidence with which we can rule out inferred EBL amplitudes in the literature, but a brighter-ZL, weaker-EBL interpretation is favored by our data at modest significance.

10.2. Evidence for an Additional IPD Component?

We introduced a single free parameter that posits the addition of a ZL offset. The DIRBE experiment, on which the Kelsall model is based, was a NASA mission operated in low Earth orbit. The model was generated by fitting a geometrical parameterization to the annual modulation in DIRBE-measured intensity. This natural variation arises from the change in line of sight through the inclined IPD cloud as the Earth orbits around the Sun and through the cloud. Because all data constraints are derived from a differential signal, the Kelsall model is by design insensitive to any isotropic signatures, which contribute intensity that does not vary with an annual modulation as observed from 1 au.

The Wright model was designed to include all observed flux, under the assumption that the total sky brightness at 25 μm , where the ZL peaks, was entirely from the ZL. The shorter wavelength intensities were then predicted by spectral extrapolation using the measured ZL color. Therefore, the Wright model would include flux from an isotropic component at the cost of potentially attributing some EBL flux at 25 μm to the ZL.

The idea of an isotropic ZL component that would evade detection in geometrical studies has been posited by several studies in the literature. Chary & Pope (2010), in their investigation into far-IR background sources suggested their

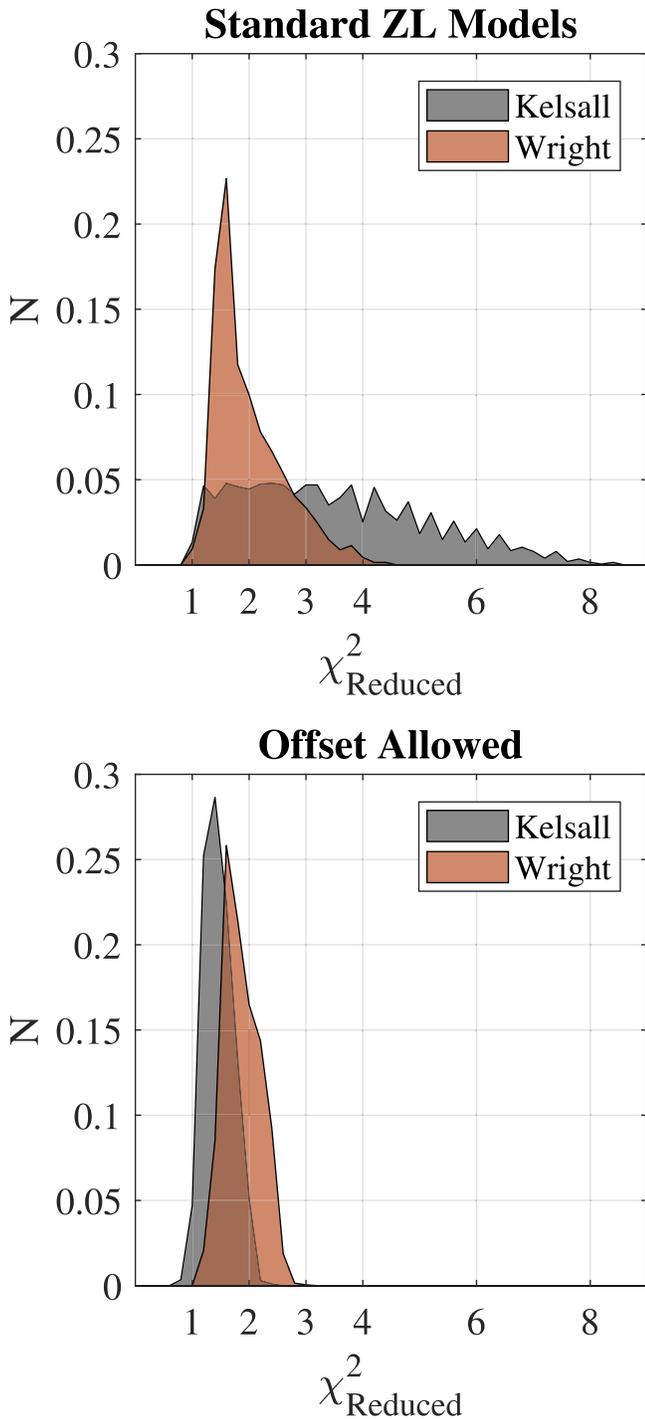


Figure 18. Reduced χ^2 distributions combining statistical and systematic errors as a test of goodness of fit to both the Kelsall (black) and Wright (red) models. Top: evaluating A_{ZL} compared to the two ZL models. Bottom: after including an additional degree of freedom represented by a best fit offset.

data could be explained by the existence of thermal emission from a 53 ± 16 K diffuse source around the outer solar system (>200 au). However, Tsumura (2018) argue through a series of model fits to the thermal emission that the NIR flux contribution of such a feature must be exceedingly small, on the scale of $1 \text{ nW m}^{-2} \text{ sr}^{-1}$ at 12500 \AA , which would be undetectable in this study. The calculations in Tsumura (2018)

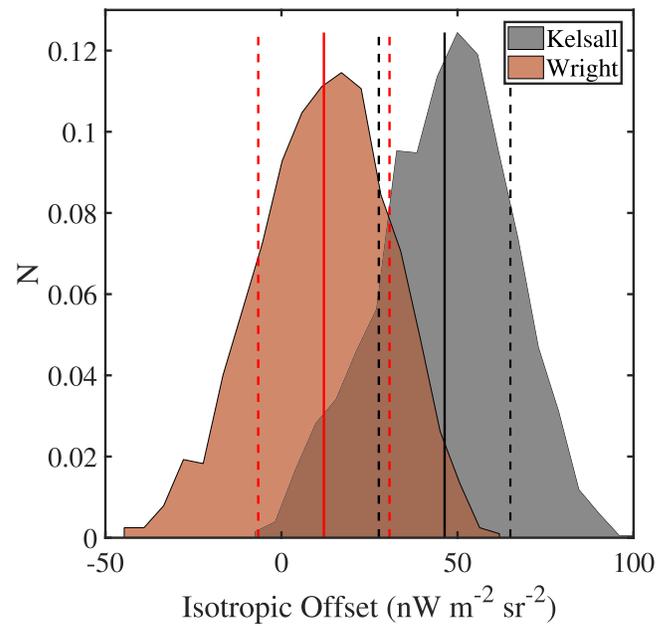


Figure 19. Distributions of inferred 12500 \AA values for a ZL offset for the Kelsall (black) and Wright (red) model predictions. The mean and 1σ range are denoted with the solid and dashed lines, respectively. The Wright model is consistent with zero to within 1σ and the Kelsall model shows an offset 2.4σ above zero.

are limited to ZL components in the outer solar system, and do not constrain components at 1 au from the Sun.

Recent dynamical simulations of the IPD such as those presented in Poppe (2016) and Nesvorný et al. (2010) predict a heliocentric isotropic IPD distribution in the inner solar system supplied by debris from long-period Oort-cloud comets (OCC) dynamically mixed in orbital space. Nesvorný et al. (2010) found their model fits to mid-infrared IRAS data were dramatically improved when including this OCC component containing $\sim 5\%$ of the IPD residing in an isotropic cloud in the inner solar system. The Kelsall geometrical model contains a smooth cloud, a series of three bands, a solar ring and an Earth-trailing blob, but does not contain a component resembling the OCC posited by Poppe (2016) and Nesvorný et al. (2010).

Sano et al. (2020) presented a reanalysis of DIRBE data, which examined the sky brightness modulations as a function of solar elongation. Including dependence on the angle of the scattering function led them to the conclusion that a spheroidal ZL component in the inner solar system that was not included in the Kelsall model improves consistency with the data. They fit two models, with the brighter suggesting an isotropic ZL amplitude as bright as $19.45 \pm 1.99 \text{ nW m}^{-2} \text{ sr}^{-1}$ at 12500 \AA attributed to the OCC component.

Our findings based on nine fields observed over three flights support a similar hypothesis, with an additional $46 \pm 19 \text{ nW m}^{-2} \text{ sr}^{-1}$ of ZL extrapolated to 12500 \AA . However, we cannot meaningfully test for isotropy. The OCC component described by Poppe (2016) and Nesvorný et al. (2010) is spheroidal but centered at the Sun and its intensity decreases slowly with heliocentric distance at 1 au. While not isotropic when viewed from Earth orbit, the annual modulation of such a component is minimal. We consider the OCC origin to be the most likely explanation of the amplitude measured by CIBER NBS.

11. Considerations for Future Measurements with this Technique

ZL removal remains the dominant systematic error limiting EBL measurement accuracy in the NIR. The measurement is fundamental to cosmology, and reconciliation of absolute spectrophotometry with gamma-ray indirect measurements must be arrived at for consensus in the community.

The achieved ZL accuracy in the measurements presented here is largely limited by the short duration of a sounding rocket flight. Recently, a range of new opportunities for spaced-based small-aperture photometric measurements have arisen, most notably in the realm of cubesats. As an exercise, we consider a cubesat NBS experiment with the same wavelength and bandwidth as ours implemented with modest modern upgrades.

1. An aperture of 10 cm fills a standard unit. This provides a factor of 1.75 in collecting area over the NBS.
2. Replace the detector with a modern 2048×2048 format array with the plate scale set such that a pixel is $6''$ large. This reduces the etendue of each pixel substantially, but would allow for masking of stars down to $M_{AB} \sim 17$ while maintaining $>50\%$ pixels and reducing the residual FISL below $1 \text{ nW m}^{-2} \text{ sr}^{-1}$. The signal-to-noise impact of loss of photons to solid angle reduction is mitigated by the vast reduction in correlated double sample (CDS) noise over the PICNIC arrays, which had $28e^-$ CDS and the $64\times$ improvement in number of pixels to coadd. For simplicity, we can assume a factor of 2 improvement in CDS, and further is achievable if a switch to CCDs is made. The FOV in this configuration is reduced to 3.5 days on a side, which dramatically reduces the spurious signal from ZL gradients and DGL structure.
3. Increase exposure times threefold to 150 s.

With the configuration listed above, the statistical uncertainty in inferred absolute ZL amplitude could be reduced below the crucial 1σ $1 \text{ nW m}^{-2} \text{ sr}^{-1}$ threshold with only ~ 100 fields. The number of measured fields would likely be limited by bandwidth considerations. A month in low Earth orbit could improve on this paper by two orders of magnitude, and would be limited by the ability to absolutely calibrate the instrument.

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