

## Research Article

# Some Similarity between Contractions and Kannan Mappings

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Contractions are always continuous and Kannan mappings are not necessarily continuous. This is a very big difference between both mappings. However, we know that relaxed both mappings are quite similar. In this paper, we discuss both mappings from a new point of view.

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## 1. Introduction

Let  $(X, d)$  be a metric space and let  $T$  be a mapping on  $X$ . Then  $T$  is called a *contraction* if there exists  $r \in [0, 1)$  such that

$$d(Tx, Ty) \leq rd(x, y) \quad (1.1)$$

for all  $x, y \in X$ .  $T$  is called *Kannan* if there exists  $\alpha \in [0, 1/2)$  such that

$$d(Tx, Ty) \leq \alpha d(x, Tx) + \alpha d(y, Ty) \quad (1.2)$$

for all  $x, y \in X$ . We know that if  $X$  is complete, then every contraction and every Kannan mapping have a unique fixed point, see [1, 2]. We know that both conditions are independent, that is, there exist a contraction, which is not Kannan, and a Kannan mapping, which is not a contraction. Thus we cannot compare both conditions directly. So we compare both indirectly.

*Fact 1*

Banach fixed-point theorem, which is often called the Banach contraction principle, is very important because it is a very forceful tool in nonlinear analysis. We think that Kannan fixed-point theorem is also very important because Subrahmanyam [3] proved that Kannan theorem characterizes the metric completeness of underlying spaces, that is, a metric space  $X$  is complete if and only if every Kannan mapping on  $X$  has a fixed point. On the other hand, Connell [4] gave an example of a metric space  $X$  such that  $X$  is not complete and every contraction on  $X$  has a fixed point. Thus the Banach theorem cannot characterize the metric completeness of  $X$ . Therefore, we consider that the notion of contractions is stronger from this point of view.

*Fact 2*

Using the notion of  $\tau$ -distances, Suzuki [5] considered some weaker contractions and Kannan mappings and proved the following.

- (i) If  $T$  is a contraction with respect to a  $\tau$ -distance, then  $T$  is Kannan with respect to another  $\tau$ -distance.
- (ii) If  $T$  is Kannan with respect to a  $\tau$ -distance, then  $T$  is a contraction with respect to another  $\tau$ -distance.

That is, both conditions are completely the same.

Recently, Suzuki [6] proved the following theorem, see also [7].

**Theorem 1.1** (see [6]). *Define a nonincreasing function  $\theta$  from  $[0, 1)$  onto  $(1/2, 1]$  by*

$$\theta(r) = \begin{cases} 1 & \text{if } 0 \leq r \leq \frac{1}{2}(\sqrt{5} - 1), \\ \frac{1-r}{r^2} & \text{if } \frac{1}{2}(\sqrt{5} - 1) \leq r \leq \frac{1}{\sqrt{2}}, \\ \frac{1}{1+r} & \text{if } \frac{1}{\sqrt{2}} \leq r < 1. \end{cases} \quad (1.3)$$

*Then for a metric space  $(X, d)$ , the following are equivalent:*

- (i)  $X$  is complete,
- (ii) every mapping  $T$  on  $X$ , satisfying the following, has a fixed point: there exists  $r \in [0, 1)$  such that  $\theta(r)d(x, Tx) \leq d(x, y)$  implies  $d(Tx, Ty) \leq rd(x, y)$  for all  $x, y \in X$ .

*Remark 1.2.*  $\theta(r)$  is the best constant for every  $r$ .

The purpose of this paper is to prove a Kannan version of Theorem 1.1. Then we compare the theorem (Theorem 2.2) with Theorem 1.1 and attempt to judge which is stronger from our new point of view.

## 2. Kannan mappings

Throughout this paper we denote by  $\mathbb{N}$  the set of all positive integers and by  $\mathbb{R}$  the set of all real numbers.

In this section, we prove our main result. We begin with the following lemma.

**Lemma 2.1.** *Let  $(X, d)$  be a metric space and let  $T$  be a mapping on  $X$ . Let  $x \in X$  satisfy  $d(Tx, T^2x) \leq rd(x, Tx)$  for some  $r \in [0, 1)$ . Then for  $y \in X$ , either*

$$\frac{1}{1+r}d(x, Tx) \leq d(x, y) \quad \text{or} \quad \frac{1}{1+r}d(Tx, T^2x) \leq d(Tx, y) \quad (2.1)$$

holds.

*Proof.* We assume

$$\frac{1}{1+r}d(x, Tx) > d(x, y), \quad \frac{1}{1+r}d(Tx, T^2x) > d(Tx, y). \quad (2.2)$$

Then we have

$$\begin{aligned} d(x, Tx) &\leq d(x, y) + d(y, Tx) \\ &< \frac{1}{1+r}(d(x, Tx) + d(Tx, T^2x)) \\ &\leq \frac{1}{1+r}(d(x, Tx) + rd(x, Tx)) = d(x, Tx). \end{aligned} \quad (2.3)$$

This is a contradiction. □

The following theorem is a Kannan version of Theorem 1.1.

**Theorem 2.2.** *Define a nonincreasing function  $\varphi$  from  $[0, 1)$  into  $(1/2, 1]$  by*

$$\varphi(r) = \begin{cases} 1 & \text{if } 0 \leq r < \frac{1}{\sqrt{2}}, \\ \frac{1}{1+r} & \text{if } \frac{1}{\sqrt{2}} \leq r < 1. \end{cases} \quad (2.4)$$

*Let  $(X, d)$  be a complete metric space and let  $T$  be a mapping on  $X$ . Let  $\alpha \in [0, 1/2)$  and put  $r := \alpha/(1 - \alpha) \in [0, 1)$ . Assume that*

$$\varphi(r)d(x, Tx) \leq d(x, y) \quad \text{implies} \quad d(Tx, Ty) \leq \alpha d(x, Tx) + \alpha d(y, Ty) \quad (2.5)$$

*for all  $x, y \in X$ , then  $T$  has a unique fixed point  $z$  and  $\lim_n T^n x = z$  holds for every  $x \in X$ .*

*Proof.* Since  $\varphi(r) \leq 1$ ,  $\varphi(r)d(x, Tx) \leq d(x, Tx)$  holds. From the assumption, we have

$$d(Tx, T^2x) \leq \alpha d(x, Tx) + \alpha d(Tx, T^2x), \quad (2.6)$$

and hence

$$d(Tx, T^2x) \leq rd(x, Tx) \quad (2.7)$$

for  $x \in X$ . Let  $u \in X$ . Put  $u_0 = u$  and  $u_n = T^n u$  for all  $n \in \mathbb{N}$ . From (2.7), we have

$$\sum_{n=1}^{\infty} d(u_n, u_{n+1}) \leq \sum_{n=1}^{\infty} r^n d(u_0, u_1) < \infty. \quad (2.8)$$

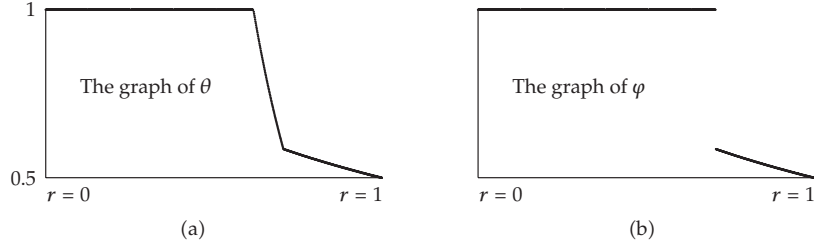


Figure 1

So  $\{u_n\}$  is a Cauchy sequence in  $X$  and by the completeness of  $X$ , there exists a point  $z$  such that  $u_n \rightarrow z$ .

We next show

$$d(z, Tx) \leq \alpha d(x, Tx), \quad \forall x \in X \text{ with } x \neq z. \quad (2.9)$$

Since  $u_n \rightarrow z$ , there exists  $n_0 \in \mathbb{N}$  such that  $d(u_n, z) \leq (1/3)d(x, z)$  for all  $n \in \mathbb{N}$  with  $n \geq n_0$ . Then we have

$$\begin{aligned} \varphi(r)d(u_n, Tu_n) &\leq d(u_n, Tu_n) = d(u_n, u_{n+1}) \\ &\leq d(u_n, z) + d(u_{n+1}, z) \\ &\leq \frac{2}{3}d(x, z) = d(x, z) - \frac{1}{3}d(x, z) \\ &\leq d(x, z) - d(u_n, z) \leq d(u_n, x), \end{aligned} \quad (2.10)$$

and hence

$$d(Tu_n, Tx) \leq \alpha d(u_n, Tu_n) + \alpha d(x, Tx) \quad \text{for } n \in \mathbb{N} \text{ with } n \geq n_0. \quad (2.11)$$

Therefore, we obtain

$$\begin{aligned} d(z, Tx) &= \lim_{n \rightarrow \infty} d(u_{n+1}, Tx) = \lim_{n \rightarrow \infty} d(Tu_n, Tx) \\ &\leq \lim_{n \rightarrow \infty} (\alpha d(u_n, Tu_n) + \alpha d(x, Tx)) \\ &= \alpha d(x, Tx) \end{aligned} \quad (2.12)$$

for  $x \in X$  with  $x \neq z$ .

Let us prove that  $z$  is a fixed point of  $T$ . In the case where  $0 \leq r < 1/\sqrt{2}$ , arguing by contradiction, we assume that  $Tz \neq z$ . Then we have, from (2.9),

$$d(z, T^2z) \leq \alpha d(Tz, T^2z) \leq \alpha r d(z, Tz), \quad (2.13)$$

and hence

$$\begin{aligned} d(z, Tz) &\leq d(z, T^2z) + d(Tz, T^2z) \\ &\leq \alpha r d(z, Tz) + r d(z, Tz) = \frac{r + 2r^2}{1 + r} d(z, Tz) \\ &< \frac{r + 1}{1 + r} d(z, Tz) = d(z, Tz). \end{aligned} \quad (2.14)$$

This is a contradiction. Therefore, we obtain  $Tz = z$ . In the case where  $1/\sqrt{2} \leq r < 1$ , from Lemma 2.1, either

$$\varphi(r)d(u_{2n}, u_{2n+1}) \leq d(u_{2n}, z) \quad \text{or} \quad \varphi(r)d(u_{2n+1}, u_{2n+2}) \leq d(u_{2n+1}, z) \quad (2.15)$$

holds for  $n \in \mathbb{N}$ . Thus there exists a subsequence  $\{n_j\}$  of  $\{n\}$  such that

$$\varphi(r)d(u_{n_j}, u_{n_j+1}) \leq d(u_{n_j}, z) \quad (2.16)$$

for  $j \in \mathbb{N}$ . From the assumption, we have

$$d(z, Tz) = \lim_{j \rightarrow \infty} d(u_{n_j+1}, Tz) \leq \lim_{j \rightarrow \infty} (\alpha d(u_{n_j}, u_{n_j+1}) + \alpha d(z, Tz)) = \alpha d(z, Tz). \quad (2.17)$$

Since  $\alpha < 1/2$ , we have  $Tz = z$ . Therefore, we have shown  $Tz = z$  in both cases.

From (2.9), we obtain that the fixed point  $z$  is unique.  $\square$

*Remark 2.3.* Since  $\theta(r) \leq \varphi(r)$  for every  $r$ , we can consider that Kannan is stronger from our new point of view. Though  $\theta$  and  $\varphi$  are different, we remark that the graphs of  $\theta$  and  $\varphi$  are quite similar.

The following theorem shows that  $\varphi(r)$  is the best constant for every  $r$ .

**Theorem 2.4.** Define a function  $\varphi$  as in Theorem 2.2. For every  $\alpha \in [0, 1/2)$ , putting  $r = \alpha/(1 - \alpha)$ , there exist a complete metric space  $(X, d)$  and a mapping  $T$  on  $X$  such that  $T$  has no fixed points and

$$\varphi(r)d(x, Tx) < d(x, y) \quad \text{implies} \quad d(Tx, Ty) \leq \alpha d(x, Tx) + \alpha d(y, Ty) \quad (2.18)$$

for all  $x, y \in X$ .

*Proof.* In the case where  $0 \leq r < 1/\sqrt{2}$ , define a complete subset  $X$  of the Euclidean space  $\mathbb{R}$  by  $X = \{-1, 1\}$ . We also define a mapping  $T$  on  $X$  by  $Tx = -x$  for  $x \in X$ . Then  $T$  does not have a fixed point and

$$\varphi(r)d(x, Tx) = 2 \geq d(x, y) \quad (2.19)$$

for all  $x, y \in X$ . In the case where  $1/\sqrt{2} \leq r < 1$ , define a complete subset  $X$  of the Euclidean space  $\mathbb{R}$  by

$$X = \{0, 1\} \cup \{x_n : n \in \mathbb{N} \cup \{0\}\}, \quad (2.20)$$

where  $x_n = (1 - r)(-r)^n$  for all  $n \in \mathbb{N} \cup \{0\}$ . Define a mapping  $T$  on  $X$  by  $T0 = 1$ ,  $T1 = 1 - r$ , and  $Tx_n = x_{n+1}$  for  $n \in \mathbb{N} \cup \{0\}$ . Then the following are obvious:

- (i)  $d(T0, T1) = r = \alpha d(0, T0) + \alpha d(1, T1)$ ,
- (ii)  $\varphi(r)d(0, T0) \geq \varphi(r)d(x_n, Tx_n) = d(0, x_n)$  for  $n \in \mathbb{N} \cup \{0\}$ .

Also, we have

$$\begin{aligned} d(Tx_m, Tx_n) &\leq d(0, Tx_m) + d(0, Tx_n) = \alpha d(x_m, Tx_m) + \alpha d(x_n, Tx_n), \\ d(T1, Tx_n) - (\alpha d(1, T1) + \alpha d(x_n, Tx_n)) &\leq d(0, T1) + d(0, Tx_n) - (\alpha d(1, T1) + \alpha d(x_n, Tx_n)) \\ &= d(0, T1) - \alpha d(1, T1) = \frac{1 - 2r^2}{1 + r} \leq 0 \end{aligned} \quad (2.21)$$

for  $m, n \in \mathbb{N} \cup \{0\}$ .  $\square$

### 3. Generalized Kannan mappings

It is a very natural question of whether or not another fixed-point theorem with  $\theta$  exists. In this section, we give a positive answer to this problem.

**Theorem 3.1.** *Define a nonincreasing function  $\theta$  as in Theorem 1.1. Let  $(X, d)$  be a complete metric space and let  $T$  be a mapping on  $X$ . Suppose that there exists  $r \in [0, 1)$  such that*

$$\theta(r)d(x, Tx) \leq d(x, y) \quad \text{implies} \quad d(Tx, Ty) \leq r \max \{d(x, Tx), d(y, Ty)\} \quad (3.1)$$

for all  $x, y \in X$ . Then  $T$  has a unique fixed point  $z$  and  $\lim_n T^n x = z$  holds for every  $x \in X$ .

*Proof.* Since  $\theta(r)d(x, Tx) \leq d(x, Tx)$ , we have, from the assumption,

$$d(Tx, T^2x) \leq r \max \{d(x, Tx), d(Tx, T^2x)\} \quad (3.2)$$

and hence

$$d(Tx, T^2x) \leq rd(x, Tx) \quad (3.3)$$

for  $x \in X$ . Let  $u \in X$ . Put  $u_0 = u$  and  $u_n = T^n u$  for all  $n \in \mathbb{N}$ . As in the proof of Theorem 2.2, we can prove that  $\{u_n\}$  converges to some  $z \in X$ .

We next show

$$d(z, Tx) \leq rd(x, Tx) \quad \text{for all } x \in X \text{ with } x \neq z. \quad (3.4)$$

Since  $u_n \rightarrow z$ , we have  $\theta(r)d(u_n, Tu_n) \leq d(u_n, x)$  for sufficiently large  $n \in \mathbb{N}$ . Hence we obtain, from the assumption,

$$\begin{aligned} d(z, Tx) &= \lim_{n \rightarrow \infty} d(u_{n+1}, Tx) = \lim_{n \rightarrow \infty} d(Tu_n, Tx) \\ &\leq \lim_{n \rightarrow \infty} r \max \{d(u_n, Tu_n), d(x, Tx)\} = rd(x, Tx) \end{aligned} \quad (3.5)$$

for  $x \in X$  with  $x \neq z$ .

Let us prove that  $z$  is a fixed point of  $T$ . In the case where  $0 \leq r < 1/\sqrt{2}$ , we note

$$\theta(r) \leq \frac{1-r}{r^2}. \quad (3.6)$$

We will show, by induction,

$$d(T^n z, Tz) \leq rd(z, Tz) \quad (3.7)$$

for  $n \in \mathbb{N}$  with  $n \geq 2$ . When  $n = 2$ , (3.7) becomes (3.3), thus (3.7) holds. We assume  $d(T^n z, Tz) \leq rd(z, Tz)$  for some  $n \in \mathbb{N}$  with  $n \geq 2$ . Since

$$d(z, Tz) \leq d(z, T^n z) + d(T^n z, Tz) \leq d(z, T^n z) + rd(z, Tz), \quad (3.8)$$

we have  $d(z, Tz) \leq (1/(1-r))d(z, T^n z)$ , and hence

$$\begin{aligned} \theta(r)d(T^n z, T^{n+1} z) &\leq \frac{1-r}{r^2}d(T^n z, T^{n+1} z) \leq \frac{1-r}{r^n}d(T^n z, T^{n+1} z) \\ &\leq (1-r)d(z, Tz) \leq d(z, T^n z). \end{aligned} \quad (3.9)$$

Therefore, by the assumption, we have

$$d(T^{n+1} z, Tz) \leq r \max \{d(T^n z, T^{n+1} z), d(z, Tz)\} = rd(z, Tz). \quad (3.10)$$

By induction, (3.7) holds for  $n \in \mathbb{N}$  with  $n \geq 2$ . Arguing, by contradiction, we assume  $Tz \neq z$ . Then from (3.7),  $T^n z \neq z$  holds for all  $n \in \mathbb{N}$ . Then by (3.4), we have

$$d(T^{n+1} z, z) \leq rd(T^n z, T^{n+1} z) \leq r^{n+1}d(z, Tz). \quad (3.11)$$

This implies  $T^n z \rightarrow z$ , which contradicts (3.7). Therefore, we obtain  $Tz = z$ . In the case where  $1/\sqrt{2} \leq r < 1$ , as in the proof of Theorem 2.2, we can show that there exists a subsequence  $\{n_j\}$  of  $\{n\}$  such that  $\varphi(r)d(u_{n_j}, u_{n_j+1}) \leq d(u_{n_j}, z)$  for  $j \in \mathbb{N}$ . From the assumption, we have

$$d(z, Tz) = \lim_{j \rightarrow \infty} d(u_{n_j+1}, Tz) \leq \lim_{j \rightarrow \infty} r \max \{d(u_{n_j}, u_{n_j+1}), d(z, Tz)\} = rd(z, Tz). \quad (3.12)$$

Since  $r < 1$ , the above inequality implies that  $Tz = z$ . Therefore, we have shown that  $Tz = z$  in both cases.

From (3.4), we obtain that the fixed point  $z$  is unique.  $\square$

*Remark 3.2.* When the second author was proving Theorem 1.1, he did not feel that  $\theta(r)$  was natural. However, since the above proof is easier to understand how  $\theta(r)$  works, the authors can faintly feel that  $\theta(r)$  is natural.

The following theorem shows that  $\theta(r)$  is the best constant for every  $r$ .

**Theorem 3.3.** *Define a function  $\theta$  as in Theorem 1.1. Then for any  $r \in [0, 1)$ , there exist a complete metric space  $(X, d)$  and a mapping  $T$  on  $X$  such that  $T$  has no fixed points and*

$$\theta(r)d(x, Tx) < d(x, y) \quad \text{implies} \quad d(Tx, Ty) \leq r \max \{d(x, Tx), d(y, Ty)\} \quad (3.13)$$

for all  $x, y \in X$ .

*Proof.* We have already shown the conclusion in the case where  $0 \leq r \leq (1/2)(\sqrt{5}-1)$  or  $1/\sqrt{2} \leq r < 1$  because  $\varphi(r) = \theta(r)$  holds. So let us consider the case where  $(1/2)(\sqrt{5}-1) < r < 1/\sqrt{2}$ . Define a complete subset  $X$  of the Euclidean space  $\mathbb{R}$  by  $X = \{x_n : n \in \mathbb{N}\}$ , where  $x_0 = 0, x_1 = 1, x_2 = 1-r$ , and  $x_n = (1-r-r^2)(-r)^{n-3}$  for  $n \geq 3$ . Define a mapping  $T$  on  $X$  by  $Tx_n = x_{n+1}$  for  $n \in \mathbb{N}$ . Then the following are obvious:

- (i)  $d(Tx_0, Tx_1) = r = rd(x_0, Tx_0) = r \max \{d(x_0, Tx_0), d(x_1, Tx_1)\}$ ,
- (ii)  $\theta(r)d(x_0, Tx_0) \geq \theta(r)d(x_2, Tx_2) = 1-r = d(x_0, x_2)$ ,
- (iii)  $\theta(r)d(x_0, Tx_0) \geq \theta(r)d(x_n, Tx_n) = ((1-r^2)/r^2)d(x_0, x_n) \geq d(x_0, x_n)$  for  $n \geq 3$ ,
- (iv)  $d(Tx_1, Tx_2) = r^2 = rd(x_1, Tx_1)$ .

Since

$$x_3 < x_5 < x_7 < \cdots < x_0 < \cdots < x_8 < x_6 < x_4 < x_2 < x_1, \quad (3.14)$$

we have the following:

- (i)  $d(Tx_1, Tx_n) < d(x_2, x_3) = r^2 = rd(x_1, Tx_1)$  for  $n \geq 3$ ,
- (ii)  $d(Tx_2, Tx_n) - rd(x_2, Tx_2) \leq d(x_3, x_4) - r^3 = 2r^2 - 1 \leq 0$  for  $n \geq 3$ ,
- (iii)  $d(Tx_m, Tx_n) \leq d(Tx_m, Tx_{m+1}) = rd(x_m, Tx_m)$  for  $3 \leq m < n$ .

This completes the proof. □

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